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Scale invariant relationship between rainfall kinetic energy and intensity in Paris region: An evaluation using universal multifractal framework

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7 Abstract

5

6

To calculate the effect of rainfall in detaching particles and initiating soil erosion, or 8 in eroding wind turbine leading edge, it is important to measure recorded drop size distri-9 butions (DSD) and fall velocity over long period. Commonly used relationships between 10 kinetic energy (KE) and rainfall rate (R) exhibit strong dependence on the temporal reso-11 lution at which the analysis is carried out. Here we aim at developing a new scale invariant 12 relationship relying on the framework of Universal Multifractals (UM), which is widely 13 used to analyze and characterize geophysical fields that exhibit extreme variability across 14 wide range of scales. 15

Rainfall data is collected using three optical disdrometers working on different under-16 lying technologies (one Campbell Scientific PWS100 and two OTT Parsivel² instruments) 17 and operated by the Hydrology Meteorology and Complexity laboratory of École des Ponts 18 ParisTech in Paris area (France). They provide access to the size and velocity of drops 19 falling through sampling areas of few tens of cm². Such data enables estimation of rainfall 20 DSD, R and KE at various resolutions. The temporal variations of this geophysical data 21 over wide range of scales are then characterized in the UM framework, which was never 22 done for KE. A new power law relation is developed and tested against the theoretical 23

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- ²⁴ framework assuming gamma DSD for describing the dependence between *KE* and *R*. The
- ²⁵ developed equation using scale invariant features of UM does not rely on gamma DSD as-
- ²⁶ sumption, performs as well as the existing tools, and is valid not only at a single scale, but
- ²⁷ also across scales.
- 28 Keywords:
- ²⁹ rainfall intensity, rainfall kinetic energy, disdrometer, multifractal, scale invariance,
- 30 gamma DSD

31 1. Introduction

³² 1.1. On the importance of rainfall and kinetic energy

Understanding the relation between rainfall rate (R) and kinetic energy (KE) is essen-33 tial for accurate determination of various rainfall parameters and understanding their after 34 effects on surrounding ecosystem (Karlen et al., 2003). It has been well established that 35 onsite erosion of soil - splash and runoff - depends on drop size distribution (DSD) and fall 36 velocity of the spectrum (Ellison, 1944; Fernández-Raga et al., 2017). Hence, KE and R 37 are primarily used to quantify rainfall erosivity and to estimate erosion rates in universal 38 models towards sustainable land use planning (Angulo-Martínez et al., 2012; Shojaei et al., 39 2020; Mohamadi and Kavian, 2015). Erosion heavily affects agricultural sector: On on-site 40 level, it impoverishes the top soil off nutrients and organic matter along with their water 41 holding capacity; this in turn increases the use of fertilizers and hence causes pollution at 42 the recipient end of off-site erosion. Further, on off-site level, soil transport by erosion can 43 trigger flood events through silting up of basins and rivers (Pimentel, 2006; Enne et al., 44 2000). Rainfall erosivity is a key parameter in various erosion models such as US based 45 Universal Soil Loss Equation (USLE, Smith and Wischmeier, 1962) and its revised ver-46 sion (RUSLE, Renard et al., 1997), South Korean based SEMMA models for calculating 47 soil loss (Deog Park et al., 2012), and in European models such as EUROSEM, WaTEM 48 etc. that account for sediment transportation along soil loss (Morgan et al., 1998; Van Oost 49 et al., 2000; Kirkby et al., 2008, an advance on USLE). Most of these frameworks use KE 50 as the major quantifying factor for estimating erosivity at spatial scales as rainfall KE rep-51 resents the total energy available for detachment and transport of soil on surface of impact. 52 As direct measurement of KE is limited to specific geographical locations possessing re-53 quired instrumental capabilities, understanding the relationship between KE and the more 54

⁵⁵ commonly available rainfall parameter, *R*, is important in estimating the former in more ⁵⁶ places.

Accurate estimation of rainfall KE is also important in understanding and mitigating 57 leading-edge erosion (LEE) on wind turbine blades. Erosion damage reduces aerodynamic 58 performance of blades resulting in reduced annual energy production and increased down-59 time (Keegan et al., 2013). Though LEE involves a multitude of atmospheric factors, 60 impact velocity and amount of precipitation have been established as some of the major 61 external factors in erosion (Herring et al., 2019). As in soil erosion, larger drops with 62 greater mass and vertical terminal velocity causes a disproportionate amount of erosion in 63 LEE also. Rainfall KE helps to quantify the impact of droplets hitting perpendicular to the 64 surface and hence rainfall erosion on blades which is the accumulated aggregate of multi-65 ple impacts stochastically distributed over the surface of the coated laminate (Bech et al., 66 2018). In Whirling arm rain erosion test (WA-RET) (ASTM-G73-10, 2017; Liersch and 67 Michael, 2014; DNVGL-RP-0171, 2014), the industrial standard for measuring durability 68 of leading-edge structures, specimens are subjected in controlled velocity and rain condi-69 tions to assess the damage caused by droplet impacts (Bech et al., 2018). Considering the 70 rapid growth of offshore wind industry as sustainable clean energy solution in the Amer-71 icas and Asia with monsoon seasons, proper representation of KE and R is important in 72 quantifying LEE in wind turbines. 73

74 1.2. Review of existing relations and need for a scale invariant representation

Application of erosion frameworks such as USLE or RUSLE poses uncertainties because of their empirical basis which has single or limited measurement locations and specific methods of data collection. These frameworks take *KE* as the major quantifying factor for erosivity, and employ various corrections to mitigate overestimation at low inten-

sity rainfall as smaller droplets are less effective in soil detachment (van Dijk et al., 2002). 79 Another commonly used erosivity index is rainfall momentum, but it has been shown that 80 for natural rainfall they exhibit similar relationship with rainfall intensity (Hudson, 1971). 81 These models are based on traditional two parameter exponential rain drop size distribu-82 tion models developed from smaller sample collection methods such as flour pellets or stain 83 paper (Laws and Parsons, 1943; Marshall and Palmer, 1948). Later studies using multi pa-84 rameter radiometry and disdrometers have shown improvements in measurement if DSD is 85 assumed to be a three parameter gamma distribution (Ulbrich, 1983). Gamma distribution 86 assumes fewer large drops in rain and represents a narrower DSD than the exponential one, 87 and thereby reduces the overestimation of KE by the latter. For recording DSD and in turn 88 obtaining empirical KE, disdrometers are commonly used in meteorological campaigns, 89 where fall velocity is either directly measured or estimated from empirical relations (Gunn 90 and Kinzer, 1949; Atlas et al., 1973). 91

There has been various studies towards accurate representation of KE - R relationship. 92 Fox (2004) demonstrates the impact of formulation of DSD in calculation of KE and hence 93 on erosion. Smith and Wischmeier (1962) proposed a logarithmic function based on DSD 94 formulation by Laws and Parsons (1943) and terminal velocity by Gunn and Kinzer (1949). 95 It was used in modelling erosion in USLE, which was later replaced by continuous expo-96 nential functions in revised USLE approach (Renard et al., 1997; Brown and Foster, 1987). 97 Other proposed forms of KE - R equations were linear (Kinnell, 1981; Sempere-Torres 98 et al., 1998), polynomial (Carter, 1979) and power-law (Park et al., 1982). Critical litera-99 ture appraisal by van Dijk et al. (2002) on various KE - R relations lists measurement tech-100 niques and procedures, sampling biases, interpretation methods and storm types as reasons 101 for discrepancies and suggests another exponential based predictive equation. More recent 102

reviews such as Angulo-Martínez and Barros (2015), Wilken et al. (2018), Mineo et al. (2019) shows lack of universality among various KE - R relationships (logarithmic, linear, power law and exponential) using disdrometer measurements and modelling at different geographic stations, meteorologic conditions and time aggregation used for calibration.

Most of the empirical formulations express KE as volume specific - kinetic energy 107 per unit area and mm of rainfall or KE_{mm} (Jm⁻²mm⁻¹) due to prevalence of non auto-108 mated measurements and lack of accuracy in determining exposure time. But expression 109 of volume specific kinetic energy creates a statistical artefact (spurious ratio correlation) in 110 KE - R relationship due to the inclusion of $R (mmh^{-1})$ in the KE_{mm} expression. Salles et al. 111 (2002) suggests usage of more consistent time specific KE or KE_{time} (J m⁻² h⁻¹) that has 112 been shown to produce less heteroscedasticity than corresponding $KE_{mm} - R$ scatter plots. 113 For representing erosion, KE_{time} has been expressed as the rate of expenditure of rain-114 fall kinetic energy (Kinnell, 1981), rainfall or kinetic power (Smith and De Veaux, 1992) 115 and rainfall kinetic energy flux density (Steiner and Smith, 2000). The two expressions 116 are related to each other through rain intensity and hydrological studies usually harmonize 117 KE - R relationships with KE_{time} . 118

$$KE_{time} = R \times KE_{mm} \tag{1}$$

In this paper the expressions for *KE* are derived and analyzed in the form of KE_{time} unless otherwise specified.

¹²¹ Due to variations in methodologies used and DSD characteristics during measurement, ¹²² different functional forms show different behaviour towards KE - R estimation. Though ¹²³ commonly preferred, exponential relations have been shown to underestimate KE_{time} for ¹²⁴ lower intensities of rainfall (Carollo and Ferro, 2015). Power-laws that predict kinetic

energy well at lower intensities tend to overestimate the same for higher intensities. Log-125 arithmic curves are limited in their usage though they fit low and high intensity KE rather 126 decently (van Dijk et al., 2002). Further due to the empirical formulation, when it comes to 127 expressing KE_{time} vs R, most of these mathematical equations fail to have much physical 128 justification. Using generalized scaling formulation that expresses various existing DSD 129 models as it's special cases (Torres et al., 1994; Sempere-Torres et al., 1998), Salles et al. 130 (2002) found that power law is the most suitable function to relate KE_{time} and R from a 131 microphysical point of view. The parameters (prefactor and exponent) of power law are 132 related to rain type, geographical location and measuring technique. Shin et al. (2016) has 133 proposed a representative power law based on the ideal assumption that the drop-size is 134 uniformly distributed under the constant rainfall intensity. 135

136 1.3. Purpose of paper

Current literature on KE and R lacks a common consensus on the usage of expres-137 sion that is valid across various scales of measurement, hydro-meteorological regimes or 138 observation techniques. There is an increased focus on research characterizing rainfall mi-139 crophysics at local and regional scales (Petan et al., 2010). Here we examine the variation 140 of KE and R for over 7 years in Paris region using continuous data from three disdrom-141 eters from two different manufacturers. Using the framework of Universal Multifractal 142 (UM) (Schertzer and Lovejoy, 1987), efforts were made to characterize the variability of 143 KE_{time} and R on event based and year based analysis, and to formulate a scale invariant 144 relation based on power law relationships. Multifractals allow characterization of com-145 plex geophysical fields with a limited number of scale invariant exponents (see Schertzer 146 and Tchiguirinskaia, 2020, for a recent review). Multifractal behaviour of measured rain-147 fall has been abundantly studied previously (see Gupta and Waymire, 1990; Kumar and 148

Foufoula-Georgiou, 1993; Deidda et al., 1999; Olsson and Niemczynowicz, 1996; García-149 Marín et al., 2008; Langousis et al., 2009; Emmanouil et al., 2020, for some examples 150 among others). Wolfensberger et al. (2017) & Schertzer and Lovejoy (2011) used UM in 151 climatological analysis of precipitation - modelled and actual - in relation to external geo-152 graphical and meteorological descriptors. Checking the validity of UM framework on KE, 153 which was never done to the knowledge of the authors, is a first goal of the paper. The 154 main goal of this paper is to explore the possibility of establishing a physically based scale 155 invariant power law relationship between KE and R using the UM framework, without hav-156 ing to rely on strong assumptions on DSD shape; and compare its performance with more 157 classical approach. 158

This article is structured as follows. In section 2 the methodology used is detailed. 159 First, the commonly used framework of gamma distributed DSD which yields a power-law 160 relation is reminded along with the associated parameters' estimation techniques. Then, the 161 process to identify power-law relation in the UM framework is explained after a required 162 reminder on the theoretical underlying basis. Similarly, the associated parameters' estima-163 tion techniques, which will be implemented, are described. Section 3 includes details of 164 data collection and quality control. Results are discussed in section 4 where validity of 165 formulated relation is tested and contrasted over different types of rain events. The final 166 section, section 5, concludes the study and summarizes the main observations. 167

168 2. Methodology

169 2.1. Theoretical relation assuming gamma distributed DSD

170 2.1.1. Rainfall microstructure and commonly used gamma distribution

Rainfall is measured and represented as distribution of raindrops in different diame-171 ter classes or drop size distribution (DSD) and their corresponding terminal fall velocity 172 in stable air. For meteorological purposes, size distribution of raindrops is represented as 173 mean number of drops per unit volume in a particular diameter (more precisely equivo-174 lumic diameter, i.e. the diameter of a drop with the same volume but a spherical shape) 175 range between D and D + dD, $N_{\nu}(D)$ (m⁻³ mm⁻¹). However, in hydrological studies, DSD 176 measured by ground based devices such as disdrometers or optical spectrometers are rep-177 resented as mean number of raindrops in a particular diameter range arriving at a surface 178 per unit area per unit time, $N_A(D)$ (m⁻² mm⁻¹ s⁻¹). If effects of wind, turbulence and 179 raindrop interactions are neglected, $N_{\nu}(D)$ and $N_A(D)$ are related as follows (Uijlenhoet 180 and Stricker, 1999): 181

$$N_A(D) = v(D)N_v(D) \tag{2}$$

where v(D) represents the terminal fall velocity (ms⁻¹) as a function of the equivalent spherical diameter of raindrop D (mm).

Traditional mathematical expressions describing $N_{\nu}(D)$ such as exponential (Marshall and Palmer, 1948), weibull (Best, 1950), gamma (Ulbrich, 1983) and lognormal (Feingold and Levin, 1986) can be expressed as particular case of general formulation proposed by Sempere-Torres et al. (1998). For the scope of this paper, gamma distribution of DSD, which has been recognized to better represent natural rain, will be considered (Ulbrich, 189 1983). In this framework :

$$N_{\nu}(D) = N_0 D^{\mu} e^{-(\Lambda D)} \tag{3}$$

where $N_{\nu}(D)$ is in m⁻³ mm⁻¹, D in mm, N_0 (in m⁻³ mm^{-1- μ}), μ and Λ (in mm⁻¹) are distribution parameters measuring raindrop concentration, mean size and shape of spectrum respectively. Λ is usually expressed with the help of the median volume diameter D_0 as $\Lambda = (3.67 + \mu)/D_0$.

¹⁹⁴ 2.1.2. Theoretical power law relation between R and KE

Rainfall intensity or rain rate (R, in mm h⁻¹) can be calculated from $N_A(D)$ using following expression (Steiner and Smith, 2000) :

$$R = 3.6 \times 10^{-3} \frac{\pi}{6} \int_0^\infty D^3 N_A(D) dD$$
(4)

¹⁹⁷ Kinetic energy per unit area per unit time (KE_{time} in J m⁻² h⁻¹) of falling drops can also ¹⁹⁸ be expressed in terms of measured $N_A(D)$ as follows (Steiner and Smith, 2000) :

$$KE = 3.6 \times 10^{-6} \frac{\pi \rho}{12} \int_0^\infty D^3 v^2(D) N_A(D) dD$$
(5)

where ρ is density of water in standard conditions in (kg m⁻³).

Though there are more sophisticated equations proposed in the literature for v(D), for simplicity in calculation, here we are following the widely used power law formulation by Atlas and Ulbrich (1977). Uijlenhoet (2001) demonstrated it has the only functional form consistent with power law relationship between rainfall related parameters :

$$v(D) = c D^g \tag{6}$$

 $_{204}$ $c = 3.78 \,\mathrm{m \, s^{-1} mm^{-g}}$ and g = 0.67 (with v in ms⁻¹ and D in mm).

Most of the rainfall parameters can be approximated as moments of the DSD; and when DSD follows gamma model, the n^{th} moment, M_n can be computed as (Atlas and Ulbrich, 1977) :

$$M_n = \int_0^\infty D^n N(D) d(D) = N_0 \Lambda^{-(\mu+n+1)} \Gamma(\mu+n+1)$$
(7)

where $\Gamma(\alpha)$ is the complete gamma function

$$\Gamma(\alpha) = \int_0^\infty x^{\alpha - 1} e^{-x} dx, \quad \text{where } \alpha > 0.$$
(8)

Substituting equations 2, 3, 6 and 7, and solving the integral gives reduced expressions for *KE* and *R* in terms of gamma function;

$$R = 6 \times 10^{-4} \pi c N_0 \frac{\Gamma(4 + g + \mu)}{\Lambda^{(4 + g + \mu)}}$$
(9)

$$KE = 3.6 \times 10^{-6} \frac{\rho \pi c^3}{12} N_0 \frac{\Gamma(4 + 3g + \mu)}{\Lambda^{(4 + 3g + \mu)}}$$
(10)

This reduction using gamma function enables representation of *KE* and *R* in the form of a power law as follows :

$$KE = bR^a \tag{11}$$

213 where

$$a = \frac{4+3g+\mu}{4+g+\mu}$$

$$b = 5 \times 10^{-4} \rho c^2 \left[6\pi c N_0 \times 10^{-4} \right]^{1-a} \frac{\Gamma(4+3g+\mu)}{(\Gamma(4+g+\mu))^a}$$
(12)

The final expression follows the same pattern as that by Salles et al. (2002) based on 214 generalized DSD and that of Uijlenhoet and Stricker (1999) based on exponential DSD. 215 When $\mu = 0$ gamma distribution for DSD becomes a simple Marshall and Palmer negative 216 exponential parameterization representation of DSD (Marshall and Palmer, 1948) with Eq. 217 11 becoming $KE = 8.539R^{1.287}$. Same values were obtained for exponent 'a' and pre-factor 218 'b' using the general function proposed by Salles et al. (2002) for Marshall and Palmer ap-219 proximation. Closer value of exponential coefficient were also reported by Uijlenhoet and 220 Stricker (1999) in a power law formulation based on Marshall and Palmer (1948) approxi-221 mation of DSD and power law dependence of rain drop terminal velocity, Eq. 6 (Atlas and 222 Ulbrich, 1977). 223

Many simplifications were followed in this formulation of KE-R relation as a power 224 law (Eq. 11). Gamma DSD is notably assumed as well as a power law form for terminal 225 fall velocity as function of diameter. This approximation shows limitations at higher val-226 ues of diameter (D > 5 mm) and doesn't account for atmospheric turbulence or updrafts 227 and downdrafts (Adirosi et al., 2016). Effect of truncation errors in measurement is not 228 considered. The formulation also ignores the effect of horizontal wind velocity and sur-229 face impact angle of rain drops. Some authors tend to consider normalized spectra of DSD 230 (Testud, 2001) that requires only two parameters to describe the DSD; it was also not con-231 sidered here for the sake of simplicity in deriving a theoretical relation between KE and R. 232 It should be noted that although widely accepted as the best representation of natural DSD, 233

gamma function also has associated errors that exists outside experimental methodology
and sampling (Adirosi et al., 2014).

236 2.1.3. Estimation of power law coefficients from gamma DSD parameters

As mentioned before, most rainfall parameters can be expressed as moments of the DSD according to Eq. 7. The right hand side of the equation is specific to the non normalized three parameter gamma distribution considered here, as shown in Eq. 3. In practice DSD is not measured continuously but for discrete diameters D_i . As a consequence, the estimated moments $\hat{M_n}$ of order *n* are computed thanks to the following discrete sum rather than previous integral :

$$\hat{M}_n = \sum_{i=1}^{N_{class}} D_i^n N_i(D_i) \Delta D_i \qquad [\mathrm{mm}^n \mathrm{m}^{-3}]$$
(13)

where D_i is the diameter of droplet in class i, $N_i(D_i)$ is the drop size distribution (estimation discussed later in Eq. 26), ΔD_i is the width of diameter class i and N_{class} the total number of diameter classes.

Investigation of various DSD parameter estimating methods by Cao and Zhang (2009) 246 highlighted the risk in usage of maximum likelihood and L-moment estimators for pro-247 cessing data with truncation in lower end of DSD spectra. As all disdrometers are limited 248 by some minimum value of measurable diameter D_{min} (> 0), it is advisable to use tradi-249 tional method of moments (Brawn and Upton, 2008). Although the choice of moments for 250 proper parameters estimation with the method of moments is a relevant topic, it is outside 251 the scope of this paper. Hence, authors relied on the existing literature. More precisely, 252 although higher DSD moments are considered to be associated with higher errors, the ten-253 dency of lower errors with middle order moments was shown later in Smith et al. (2009) 254

(using radar measurements) and Cao et al. (2008) (using joint disdrometer-radar observa-255 tions). Cao and Zhang (2009) evaluated the performance of various moment estimators 256 using simulations of gamma DSD (with a more realistic estimation of errors) and found 257 that second, third and fourth moments (M234) as the best overall performer for estimating 258 R. Konwar et al. (2014) (M234) and Huang et al. (2021) (even higher order moments - 2,3 259 and 6) are some recent examples of using middle order moments while analysing data from 260 same disdrometer make as the one in current study (OTT Parsivel²). Hence, it was chosen 261 to employ these moments for computing gamma DSD parameters: μ , N_0 and Λ (refer Eq. 262 7). Specific moment equations are provided in the appendix (Appendix B). These parame-263 ters are then introduced in Eq. 12 to derive the expected power law parameters assuming a 264 gamma DSD. 265

Variation of *a* and *b* with DSD parameters is examined with available data set in section
4 for different type of rainfall events.

268 2.2. Theoretical relation between multifractal fields in UM framework

269 2.2.1. Overview of the theoretical framework

The framework of Universal Multifractals (UM) enables to characterize the extreme 270 variability of geophysical fields across scales, with the help of a limited number of parame-271 ters with physical meaning (Schertzer and Lovejoy, 1987). It relies on the assumption that 272 these fields are generated through an underlying multiplicative cascade. Such behaviour 273 is assumed to be inherited from the scale invariant features of the Navier-Stokes equa-274 tions, but has not yet been formally showed. Consequently, statistical properties of fields 275 are conserved in all scales. In this study, time specific kinetic energy and rainfall intensity 276 from disdrometer measurements are analyzed using UM. Review by Schertzer and Lovejoy 277 (2011) discusses the techniques and methodologies employed in more detail. 278

For analysis in UM framework, the field in consideration is normalized (divided by 279 its mean value) and its total size in terms of numerical values is restricted to be a power 280 of two. The field can be one or two dimensional; since current study involves only time 281 series we will be limiting our discussion to single dimension. Let us consider a normalized 282 conservative field (an additional parameter for non-conservative fields is introduced later) 283 ε_{λ} at resolution λ . Resolution λ is the ratio of *L*, the outer scale, to *l*, the observational 284 scale. Let us first consider the occurrence pattern of the field, i.e. the same field with 1 for 285 strictly positive values and 0 otherwise. If the field is fractal, then the probability p that 286 a segment of length l intersects the field (p is the probability of occurrence of non zero 287 elements in the total binary field) scales with resolution as follows: 288

$$p = \frac{\lambda^{D_f}}{\lambda^D} = \lambda^{-c_f} \tag{14}$$

where $c_f = D - D_f$, the fractal co-dimension of the field. The fractal dimension D_f indicates how the binary field (rain and no rain in this case) fills the available space in a scale invariant way. As *D* is constant, in order to fully characterize the field a value of D_f for each threshold is required. This is the intuitive notion of multifractality. In order to be mathematically consistent, this characterization should actually be done with the help, not of a direct threshold at the maximum resolution, but with a scale-invariant threshold called singularity γ , and their corresponding codimension function $c(\gamma)$ as :

$$p(\varepsilon_{\lambda} \ge \lambda^{\gamma}) \approx \lambda^{-c(\gamma)} \tag{15}$$

Above equation implies that statistical moments q of the field scale with resolution (Schertzer and Lovejoy, 1987, 1988) are :

$$\langle \boldsymbol{\varepsilon}_{\lambda}{}^{q} \rangle \approx \lambda^{K(q)}$$
 (16)

where K(q) is the moment scaling function related to $c(\gamma)$ by Legendre transform (Parisi and Frisch, 1985). For a conservative field in UM framework, $K_c(q)$ can be fully characterized with only two parameters, multi-fractality index α and mean intermittency codimension C_1 .

$$K_c(q) = \frac{C_1}{\alpha - 1} \left(q^\alpha - q \right) \tag{17}$$

³⁰² C_1 measures clustering of average intensity across scales; when the field is homogeneous ³⁰³ C_1 is equal to zero. α measures how this clustering changes with respect to intensity levels; ³⁰⁴ $\alpha \in [0,2]$. Larger values of both corresponds to stronger extremes. Simulations of such ³⁰⁵ fields can be obtained by generating a levy noise with parameter α , 'coloring' it to introduce ³⁰⁶ C_1 and then taking the exponential which yields solely non-negative values.

For a non conservative field ϕ_{λ} , i.e. a field whose average $(\langle \phi_{\lambda} \rangle)$ changes with scales, a non-conservative parameter *H* is used in expression of scaling:

$$\phi_{\lambda} = \varepsilon_{\lambda} \lambda^{-H} \tag{18}$$

where ε is a conservative field characterized with C_1 and α .

³¹⁰ Positive *H* represents a smoother field which needs to be fractionally differentiated for ³¹¹ obtaining a conservative field. Conversely negative *H* represents a field in need of fractional ³¹² integration for retrieving conservative field. *H* is related to the spectral slope β , which gives ³¹³ a measurement of the correlation range. Larger β means higher contribution of large-scale ³¹⁴ phenomenon in variability of data.

$$\beta = 1 + 2H - K_c(2) \tag{19}$$

³¹⁵ 2.2.2. Estimation of scaling behaviour and UM parameters

The quality of scaling of multifractal fields can be examined using trace moment (TM) 316 where log-log plot of upscaled fields against resolution λ is taken for each moment q (Eq. 317 16). For multifractal fields, the plot is a straight line with moment scaling function K(q) as 318 slope. Quality of the scaling is given by the estimate R^2 of the linear regression. The value 319 for q = 1.5 is used as reference. Double trace moment (DTM) is a more robust version of 320 TM tailored for UM fields where the moment scaling function $K(q, \eta)$ of the field $\varepsilon_{\lambda}{}^{(\eta)}$ 321 (obtained in practice by raising ε to power η at the maximum resolution and then upscaling 322 it) is expressed as a function of multifractality index α (Lavallée et al., 1993): 323

$$\langle (\boldsymbol{\varepsilon}_{\lambda}{}^{(\eta)})^{q} \rangle \approx \lambda^{K(q,\eta)} = \lambda^{\eta^{\alpha}K(q)}$$
 (20)

From the above equation, value of α can be obtained as the slope of the linear part when $K(q, \eta)$ is represented for a given q as a function of η in log-log plot.

326 2.2.3. Power law relations in UM framework and practical implementation

If a field is UM, then a power law relation of it is also a UM field with coefficients depending upon initial UM parameters. The reasoning for power law comes from the DTM analysis in UM framework (Tessier et al., 1993; Lovejoy et al., 2008).

³³⁰ Consider two multifractal fields (ε_1 and ε_2) that are power law related by an exponent ³³¹ *a* and a prefactor *b*, as below :

$$\varepsilon_1 = b\varepsilon_2^a \tag{21}$$

From exponents in Eq. 20, K(q) of ε_1 can be expressed as follows

$$< (\varepsilon_1)^q > \approx < (\varepsilon_2^{(a)})^q > \approx \lambda^{K_{\varepsilon_2}(q,a)}$$

$$K_{\varepsilon_1}(q) = K_{\varepsilon_2}(q,a) = a^{\alpha_{\varepsilon_2}} K_{\varepsilon_2}(q)$$

$$(22)$$

Expanding K(q) with UM parameters (as in Eq. 17)

$$\frac{C_{1,\varepsilon_1}}{\alpha_{\varepsilon_1}-1}(q^{\alpha_{\varepsilon_1}}-q) = a^{\alpha_{\varepsilon_2}}\frac{C_{1,\varepsilon_2}}{\alpha_{\varepsilon_2}-1}(q^{\alpha_{\varepsilon_2}}-q)$$
(23)

From above equation, we can deduce that for if a power relation exists, the UM parameters are related as follow :

$$\alpha_{\varepsilon_1} = \alpha_{\varepsilon_2} = \alpha$$

$$C_{1,\varepsilon_1} = a^{\alpha} C_{1,\varepsilon_2}$$
(24)

In this study, both *KE* and *R* time series were analysed using UM framework. As the UM model discussed here is solely non negative, it removes all possibility of having nonnegative values for both fields in analysis. Using their UM parameters in Eq. 24, it is possible to formulate power law relationship in the format of Eq. 21. It has the same shape as the theoretical power law obtained using moments of the DSD in section 2.1, in Eq. 11. Details of disdrometer data collection and subsequent multifractal analysis are covered in upcoming sections.

343 3. Data collection and instrumentation

344 3.1. Measurement campaigns

For this study, continuously monitored data in natural conditions was obtained from 345 three optical disdrometers operating with two different principles. The devices are part 346 of the TARANIS observatory (exTreme and multi-scAle RAiNdrop parIS observatory, 347 Gires et al., 2018) of the Fresnel Platform of École des Ponts ParisTech (https://hmco. 348 enpc.fr/Page/Fresnel-Platform/en); and are operated by Hydrology Meteorology 349 and Complexity laboratory of École des Ponts ParisTech (HM&Co-ENPC). Table 1 gives 350 a brief outline of measurement campaigns. From November 2016 to September 2017 351 the instruments were moved to École Polytechnique (EP) on SIRTA (Site Instrumenté de 352 Recherche par Télédétection Atmosphérique) for a joint intensive measurement campaign 353 over the Ile-de-France region. The aforementioned location is about 38 km away from 354 ENPC towards south west of Paris. To summarise, the measurements presented in the fol-355 lowing sections involve two different types of optical disdrometers and data collected from 356 two different locations of Paris region. 357



Figure 1: Location of disdrometers in Paris area, at ENPC and EP SIRTA (basemap from openstreetmap.org)

location	start time	end time
ENPC (1)	18 Jun 2013	10 Nov 2016
EP SIRTA	14 Nov 2016	20 Sep 2017
ENPC (2)	27 Dec 2017	31 Dec 2019

Table 1: Short description of the precipitation measurement campaign selected

358 3.2. Overview of instrument functioning and outputs

The three optical disdrometers used here are two OTT Parsivel² (see Battaglia et al., 2010 or the device documentation OTT, 2014) and one PWS 100 (see Ellis et al., 2006 or the device documentation Campbell-Scientific-Ltd, 2012).

The OTT Parsivel² are occlusion based devices with a transmitter that creates laser sheet and an intercepting receiver directly aligned with it. The size (equivolumic diameter) and fall velocity are assessed from changes (decrease in amplitude of intensity and duration of the decrease) in received laser intensity due to the passing of rainfall drops through a sampling area of 54 cm². An ellipsoidal shape model with a standard relation between the ³⁶⁷ axis ratio and the equivolumic diameter are assumed for drops in the process.

The PWS100 consists of a transmitter that generates four horizontal parallel laser sheets, and two receptors which are not aligned with the transmitter. The signal received by each receptor corresponds to the light refracted by drops and contains four consecutive peaks associated with each laser sheet. From the delay between those peaks, fall velocity and diameter of the drops are estimated. PWS100 has a sampling area of 40 cm². Computations assuming spherical shape of droplets are performed here with a later correction for oblateness before final result generation (Gires et al., 2017).

Both disdrometers have a collection time step of 30 s and provide main output as a 375 matrix containing the number of drops $(n_{i,i})$ recorded during the time step Δt according 376 to classes of equivolumic diameter (index *i* defined by a centre D_i and a width ΔD_i both 377 expressed in mm) and fall velocity (index j and defined by a centre v_i and a width Δv_i , 378 both expressed in ms⁻¹). For Parsivel² there are 32 classes of ΔD_i from 0.062 mm to 24.5 379 mm and Δv_i from 0.05 ms⁻¹ to 20.8 ms⁻¹. And for PWS the same ranges from 0.05 to 380 27.2 (ΔD_i , mm) and 0.05 to 27.2 (Δv_j , ms⁻¹) in 34 classes. Width of diameter and velocity 381 classes are not similar for all classes, as they are designed to be more and more refined 382 towards smaller values. 383

From the raw matrix, the studied rainfall parameters - rain rate, drop size distribution and time specific kinetic energy were obtained using following expression for each time steps.

$$R = \frac{\pi}{6\Delta t} \sum_{i,j} \frac{n_{i,j} D_i^3}{S_{eff}(D_i)}$$
(25)

$$N(D_i) = \frac{1}{S_{eff}(D_i)\Delta D_i\Delta t} \sum_j \frac{n_{i,j}}{v_j}$$
(26)

$$KE = \frac{\rho_{wat}\pi}{6\Delta t} \sum_{i,j} \frac{n_{i,j} D_i^3 v_j^2}{S_{eff}(D_i)}$$
(27)

where $S_{eff}(D_i)$ is the sampling area of disdrometer in mm², Δt is the time step duration in hr and ρ_{wat} is the volumic mass of water (10³ kg m⁻³). $N(D_i)\Delta D_i$ gives the number of drops with a diameter in the class *i* per unit volume (in m⁻³). Details of the devices, their functioning and data collection can be found in Gires et al. (2018).

391 3.3. Data quality and filtering

For the data presented in this paper, filters suggested by various authors (Kruger and 392 Krajewski, 2002; Thurai and Bringi, 2005; Jaffrain and Berne, 2012; Gires et al., 2018) 393 were used to remove possible non-meteorological measurements (from environmental fac-394 tors such as splashing, horizontal wind etc.) on the basis of size and velocity of drops. 395 Using the disdrometer data set, two series of Multifractal analysis were performed - event 396 based and year based. For event based analysis, individual rainfall events were identified 397 with following criteria in rain intensity time series - rainfall events with a cumulative depth 398 greater than 0.7 mm and separated by at least 15 minutes of dry weather before and after. 399 From all measured events with this condition, rain rate (R), drop size distribution (DSD) 400 and kinetic energy (KE) were calculated for the three disdrometers (denoted Pars 1, Pars 2 401 and PWS hereafter). From the results further filtering was done to remove events having a 402 percentage of *nan* values (not a number - blank /missing data) > 1 % and R^2 value < 0.9, 403 for both KE and R. Remaining nans were then replaced with 0. In year based methodology, 404 continuous time series from Jan 2016 to Dec 2019 - including rain and no rain conditions 405

- were used for multifractal analysis, and results were compiled according to the year of
measurement.

There were minor lapses in continuity of data measurement from Jun 2013 to Dec 2015; 408 for that reason those time periods were not considered in continuous year based analysis 409 to avoid possible measurement biases. However, since selection of individual events are 410 not affected by that, event based analysis involves data from Jun 2013 to Dec 2019. Lesser 411 number of events can be observed in the excluded years for year based analysis in Table 412 2. Between 2016 and 2019, there were also a few days of maintenance where data was not 413 recorded - 27 Sep 2017 to 26 Dec 2017, 01 to 07 Jan 2018 and 12 to 14 Apr 2019. After 414 quality control for each disdrometer, a total of 214,665 time steps were analysed in 556 rain 415 events (total 1610 events counting all three disdrometers; data was not always available for 416 all the disdrometers, hence the lesser number) from 2013 to 2019 for event based analysis. 417 In year based analysis, a total of 3,919,680 time steps were considered from 2016 to 2019; 418 percentages of rainy time steps were about 7%, 6.6% and 5.7% for Pars 1, Pars 2 and PWS 419 respectively. 420

421 **4. Results and discussions**

422 4.1. Overview of analysis

For analysing the *KE* and *R* time series using UM framework, as explained in previous sections, two strategies were followed - event based analysis and year based analysis. For event based analysis, we identified a total of 556 rainfall events between 28 Sep 2013 and 31 Dec 2019 of which 493 events were common among all three disdrometers. For UM analysis, each time series was resized to the highest power of two in such a way that the trimmed series accommodated maximum rainfall cumulative depth and then the field was normalized. After resizing for UM analysis, length of individual events ranged from 64
to 2048 time steps, where each time step corresponds to 30 s, i.e. the recording time step
of disdrometers used. *KE* and *R* from each events were analyzed as separate fields in UM
framework. For year based methodology, similar procedure was followed for UM analysis
on year long continuous time series, for the years from 2016 to 2019.

In coming subsections, estimation of UM parameters and power law relations are illustrated using one event data for event based analysis and one year data for year based analysis. Power law coefficients were also estimated using theoretical framework with DSD parameters as mentioned in section 2.1. Variation and correspondence among coefficients determined by UM and DSD parameters are discussed thereafter and validated with data.

440 4.2. Multifractal analysis of events

For illustration of the analysis carried out, one event from 2017 for Pars 1 disdrometer, 441 that occurred on 16 September between 11:35:00 and 13:00:00 (local time) is presented 442 here. Figure 2a displays the time series of R and KE for this event, as well as KE vs. R 443 plots. The latter also shows power law fits with coefficients from UM analysis and DSD 444 parameters (explained later in this section). For this event, 171 time steps were trimmed 445 to 128 time steps along region of maximum rain occurrence of which 124 were rainy data 446 points. Trimmed and normalized KE and R were then subjected to analysis using UM 447 framework discussed in section 2.2. Initial analysis indicated values of non-conservative 448 parameter H greater than 0.5 among many events. Hence to retrieve a conservative field on 449 which the UM analysis can be implemented without bias, fluctuations of KE and R time 450 series were used (Lavallée et al. 1993). Characterization of variability in KE field for the 451 event considered here can be seen in Figure 2b with TM (Eq. 16 in log-log plot), DTM 452

graphs (Eq. 20 in log-log plot) and UM parameter values. As shown in TM and DTM 453 graphs, the field exhibits a very good multifractal behaviour with a single scaling regime 454 from 30 s to 64 min. For example, TM coefficient of determination r^2 for q = 1.5 was 455 greater than 0.99. Values of UM parameters α , C_1 , and H for KE of this particular event 456 were 1.820, 0.311 and 0.547 respectively. It should be mentioned that H computed on the 457 fluctuations of KE was found to be equal to 0.189, meaning the taking the fluctuations 458 indeed enabled retrieval of a conservative field from the original smoother field. R also 459 exhibited excellent scaling behavior and corresponding values of UM parameters α , C_1 , 460 and H for this event were 1.655, 0.229, and 0.100 respectively. 461

Figure 2: a) Time series of *R*, time series of *KE*, *KE* vs *R* graph b) and c) MF analysis graphs with *KE* and *R* (log-log plot of Eq. 16 and Eq. 20 for TM and DTM analysis respectively and log-log plot of exponents in Eq. 20 for UM parameters) for Pars 1 event 16 September 2017 11:35:00 to 13:00:00



KE and R analyzed from every event exhibited similar multifractal characteristics with 462 a unique scaling regime. The quality of scaling was examined using coefficient of deter-463 mination, R^2 for q = 1.5 in TM analysis, and as previously mentioned events with values 464 < 0.9 were discarded. 9.8 % percentage of total events were rejected on this basis. For 465 the events with good scaling behaviour, robust retrieval of multifractal parameters α , C_1 , 466 β and H was possible. For example, the assessed values of α and C_1 for both KE and R 467 time series, exhibited a maximum standard deviation (using various values of q in DTM 468 analysis) of 0.0584 and 0.0670 for measurement at EP-SIRTA and 0.0446 and 0.0443 for 469

470 measurements at ENPC.

Figure 3 displays the values of multifractality index α and mean intermittency C_1 for 471 all the studied events for both fields. It appears that the values of α for KE and R are rather 472 well distributed along the bisector. This pattern suggests a power law relation between 473 these two quantities as discussed in section 2.2 (Eq. 21) where ε_1 and ε_2 are KE and R 474 respectively (i.e. $KE = bR^a$ as in Eq. 11). The exponent of the power law a was deduced 475 from corresponding α and C_1 values of UM fields (KE and R) for every event subjected to 476 UM analysis, using the expected relations for power law related UM fields, i.e. Eq. 24. The 477 α used is the average of α_{KE} and α_R (which were anyway similar). Value of prefactor b was 478 estimated by fitting Eq. 11 at maximum resolution with estimated values of a on event's 479 KE - R graph. For the event used as illustration, we found a = 1.083 and b = 11.493. This 480 power law fit from UM parameters is displayed in Figure. 2a as KE_{UM} in the KE vs. R 481 graph. 482

Variation of computed power law exponent a and prefactor b are also shown in Fig. 3 as 483 time series of events for each year. Graphs of remaining years are provided in appendix A. 484 For 3.5 % of total events filtered, estimates of α was found to be greater than the theoretical 485 maximum (> 2); however a values for those events were found to be consistent with the 486 overall average. Despite appreciable variability in UM parameters across events, values of 487 a and b showed overall stability in the short range of values specified in graphs, suggesting 488 robustness of the estimates. Year wise average values over the events for a and b, and 489 number of events for all three disdrometers are given in Table 2. Average values of power 490 law parameters from the events that were common between the three disdrometers are also 491 shown in the same table. Comparable values of a and b were observed in both cases. A 492 clear range of variation can be observed between the two types of disdrometers. For both 493

Parsivel² the average a and b were similar and around 1.22 and 8.17 respectively, while for 494 PWS100 a values were consistently lower than that of Parsivel² at around 1.17 and b values 495 greater at 13.02. PWS generally registered slightly higher intensities than Pars 1 and Pars 2. 496 It should be mentioned that a and b seem to show a very rough correlation where values of 497 b decreases with increase in values of a. But between make of instruments, irrespective of 498 the type and number of events, values of a remains rather constant. Differences in values 499 obtained between Parsivel² and PWS is expected due to operational differences between 500 disdrometers. Such effects are also reported in Johannsen et al. (2020a) who showed biases 501 in measurement and subsequent R - KE relation due to difference in type of sensors used 502 (three optical disdrometer were used). Angulo-Martínez and Barros (2015) also highlighted 503 some differences among various Parsivel². 504



Figure 3: Year wise α and C_1 variation on event based analysis from 2016 to 2019 (remaining years are provided in appendix)

			to	tal event	S	com	mon even	its
year 2013 2014 2015 2016 2017 2018 2019	location	disdrometer	# events	avg a	avg b	# events	avg a	avg b
		Pars 1	29	1.248	9.224		1.246	9.224
2013	ENPC	Pars 2	11	1.254	9.093	11	1.254	9.093
		PWS	29	1.186	11.912		1.193	11.748
		Pars 1	84	1.207	11.548		1.207	11.548
2014	ENPC	Pars 2	84	1.186	11.065	84	1.186	11.065
		PWS	84	1.159	14.065		1.159	14.065
		Pars 1	38	1.235	9.459		1.235	9.459
2015	ENPC	Pars 2	38	1.207	8.532	38	1.207	8.532
		PWS	38	1.190	11.712		1.190	11.712
		Pars 1	87	1.238	8.802		1.238	8.802
2016	ENPC	Pars 2	87	1.253	8.069	87	1.253	8.069
		PWS	87	1.180	11.939		1.180	11.939
		Pars 1	102	1.197	10.126		1.193	10.013
2017	EP-SIRTA*	Pars 2	65	1.202	8.944	65	1.202	8.944
		PWS	104	1.176	13.238		1.151	15.282
		Pars 1	78	1.221	10.832		1.221	10.832
2018	ENPC	Pars 2	78	1.205	10.647	78	1.205	10.647
		PWS	78	1.151	15.282		1.151	15.282
		Pars 1	138	1.231	9.254		1.238	8.913
2019	ENPC	Pars 2	130	1.231	8.550	130	1.231	8.55
		PWS	141	1.165	13.024		1.649	12.960

Table 2: *a*, *b* and no. of events analysed between 2013 and 2019 according to location of measurement and disdrometer used.

* From Nov 2016 to Sep 2017 as shown in Table 1; preceding and succeeding years are adjusted accordingly, refer Table 1.

505 4.3. Multifractal analysis of continuous data (year based analysis)

To illustrate year based analysis, continuous time series and UM analysis for Pars 1 disdrometer for the year 2017 is shown in Fig. 4. Both *KE* and *R* fields showed similar multifractal features. Scaling behaviour of *KE* is shown in Fig. 4b. A unique scaling regime from 30 s to 311 days was considered.

Figure 4: a) Time series of R, time series of KE, KE vs R graph b) and c) Multifractal analysis graphs with KE and R (log-log plot of Eq. 16 and Eq. 20 for TM and DTM analysis respectively and log-log plot of exponents in Eq. 20 for UM parameters) using the year based analysis, for Pars 1, for 2017



Variation of UM parameters α and C_1 between KE and R fields as well as values of 510 power law exponent a and prefactor b (computed by fitting the relation at maximum res-511 olution) are displayed in Fig. 5. Precise values of a and b according to the year of mea-512 surement are given in Table 3 in annexes. The curve KE_{UM} in the KE vs R graph of Fig. 513 4a, shows the power law fit using UM parameters for continuous data of 2016, for Pars 1. 514 Values and trend of variation are similar to that observed for the event based analysis. This 515 confirms the robustness of the discussed power law, which is valid and retrieved not only 516 at the event scale, but also at the year scale. 517



Figure 5: a) Results from multifractal analysis on continuous year wise data set: a) α and C_1 (DTM); b) *a* and *b* values

Table 3: *a* and *b* from year based analysis, from 2014 to 2019 according to disdrometer used for measurement.

* From Nov 2016 to Sep 2017 as shown in Table 1; preceding and succeeding years are adjusted accordingly

518 4.4. Power law coefficients from DSD parameters

To understand previous findings further, values of *a* and *b* were computed from theoretical framework discussed in section 2.1. Rainfall DSD was assumed to follow gamma distribution (Eq. 3) and theoretical values of *a* and *b* (denoted as a_{DSD} and b_{DSD} from here

on for clarity) were computed as per Eq. 12 after estimating values of gamma DSD param-522 eters (μ , N_0 and Λ) with the help of method of moments. The variation of rain rate R was 523 accurately reproduced using M234 moment estimators (Fig. 8d for example). Theoretical 524 power law relation ($KE_{DSD} = b_{DSD}R^{a_{DSD}}$) was then compared with the one estimated using 525 UM analysis (represented from here on as KE_{UM} with coefficients a_{UM} and b_{UM} for clarity) 526 for every events. Average values of DSD parameters, estimation error and corresponding 527 a_{DSD} and b_{DSD} for Pars 1 events are given in Table 4 according to event's rain type (defini-528 tion introduced later). RMSE_{DSD} is the root mean square error (RMSE) between empirical 529 DSD and theoretical gamma DSD with fitted parameters (using the value for the center of 530 each diameter class D_i). It is used here as an indicator of the quality of fit of the assumed 531 gamma DSD distribution and the empirical one. For RMSE estimation only the portion of 532 DSD above 0.5 mm diameter class was considered as smaller drops have lesser contribution 533 in overall KE and R, and are associated with greater uncertainties in measurement. Also, 534 higher size drops (above 9 mm diameter class) were not observed during the events and are 535 hence not shown in DSD figures discussed after (Fig. 6 and Fig. 8). 536

Figure 6:

a) 2019 Pars 1 event where empirical DSD corresponds with gamma distribution and b) where it doesn't follow gamma distribution (DSD displayed only till diameter class around 9 mm as higher drops were not observed during the events)



Figure 6 represents two extremes cases among events from year 2019 for Pars 1: one 537 event (Fig. 6a) where empirical DSD corresponds with a gamma distribution and one 538 event (Fig. 6b) where it does not. The DSD fitting as well as the KE vs. R plots (fitted 539 with power law relation from UM analysis and DSD extraction) are also displayed. For 540 the event with empirical DSD closer to estimated gamma DSD, both power law relations 541 $(KE_{UM} \& KE_{DSD})$ are similar and show good fit. For the other event, power law relation 542 from DSD approach shows a considerable deviation from actual values of KE, with a strong 543 overestimation. Power law from UM analysis on the other hand still provides a close fit. To 544 see if there is such a trend through all the events, coefficient of determination of both KE -545 R fits were plotted against each other $(r_{UM}^2 \text{ vs } r_{DSD}^2)$ and compared using corresponding 546

values of $RMSE_{DSD}$ (Fig. 7a). Negative value of coefficient of determination for DSD (r_{DSD}^2) is due to the high difference between KE_{DSD} and empirical KE in certain events. From the plot it is evident that a generalized conclusion - theoretical values of a and b(a_{DSD} & b_{DSD}) works well in cases where empirical DSD coincides with gamma DSD is not possible. However, there were many events with good DSD correspondence with gamma, where KE_{DSD} fitted data better.

Figure 7:

a) r^2 values between KE_{UM} and KE_{DSD} for Pars1, 2019; b) r^2 values between KE_{UM} and KE_{DSDfit} (*b* from fitting of data) for Pars1, 2019 (RMSE calculated by considering only parts of DSD where drop diameter > 0.5 mm)



To investigate further this issue and given that the DSD is available for all time steps, 553 a_{DSD} and b_{DSD} were computed for each time step to study their variations within a rainfall 554 event. Figure 8 displays their temporal evolution for the event in Fig. 2. Values of pa-555 rameters, especially b_{DSD} , shows considerable variation within an event. These variations 556 basically come from variations in DSD parameters μ an N_0 as it can be seen on Fig. 8c 557 and 8f (also evident from Eq. 12), which are reflecting physical variations in the rainfall 558 process. It should be mentioned that during this event (and other events), gamma DSD 559 parameters were able to properly reproduce observed rain rate (Fig. 8d), meaning that the 560

assumption of gamma DSD distribution and the M234 moment estimator approach remains valid throughout the event(s). This suggests that the variability of a_{DSD} and b_{DSD} observed at event scale is also valid within events at much smaller scales. This could explain some of the bias previously observed with DSD approach developed in this paper.

As there were still considerable variation in r^2 values of $r^2_{KE_{DSD}}$ (Fig. 7a), especially if 565 we compare with KE_{UM} which shows better $r_{KE_{UM}}^2$ regardless the type of event, a question 566 of possible bias arises due to difference in methods of estimation of power law coefficients. 567 Unlike KE_{DSD} for which both coefficients are obtained from theoretical relation involving 568 DSD parameters, for KE_{UM} only coefficient *a* is fully estimated from UM analysis. Pref-569 actor b_{UM} is obtained by fitting the data at highest available resolution (30 s) using UM 570 estimated a_{UM} . Such discrepency may introduce a bias in the comparison between DSD 571 and UM approach to retrieving a power law. Hence, to understand this further and to make 572 a fair comparison, a new power law was considered where only a_{DSD} is obtained using Eq. 573 12 while b_{DSD} is calculated from fitting of data (denoted hereafter $b_{DSD fit}$) - $KE_{DSD fit}$. Fig-574 ure 7b shows r^2 between KE_{DSDfit} and KE_{UM} ; and it can be seen that comparable fits are 575 obtained between UM and DSD power laws regardless the nature of DSD, thus illustrating 576 the presence of bias. This can also be observed in previous KE - R plots - Fig. 2a, Fig. 4a, 577 Fig. 6a and Fig. 6b. 578

Figure 8: Variation of a_{DSD} and b_{DSD} for each time steps in an event (same event discussed in Fig. 2) a) Correspondence between empirical DSD (red) and calculated DSD (blue); d) Correspondence between empirical rainfall rate (R_{emp}) and that calculated from DSD moments (R_{DSD}) b) & e) Variation of a_{DSD} and b_{DSD} within the event

c) & f) Variation of a_{DSD} and b_{DSD} with DSD parameters N_0 and μ



579 4.5. Comparison between KE - R relations

Though the power law obtained is similar from UM and DSD analysis, they fit the data 580 differently due to difference in values of corresponding parameters. KE_{DSD} in KE vs. R 581 graph of Fig. 2a and Fig. 4a shows the power law fit using theoretical a and b (a_{DSD}) 582 & b_{DSD}), from DSD parameters for illustrated examples in event based and year based 583 analysis analysis. The difference in fit between two calculations of power law, KE_{UM} and 584 KE_{DSD} can be observed there. It can be seen from Fig. 7a that KE_{UM} gives rather good 585 fit regardless the event specific DSD shape, while r^2 value of KE_{DSD} fluctuates. However, 586 there is a limited tendency for good fit towards empirical DSD following gamma distribu-587 tion (for few events like Fig. 6). Figure 9 shows variation of a and b estimates from DSD 588 and UM for Pars 1, Pars 2 and PWS for all events in year 2019. Values of a_{UM} and a_{DSD} 589

are mostly clustered around the approx. 1.2 for all three disdrometers with no clear relation between them. On the other hand, values of b_{UM} and b_{DSD} are more spread out, ranging approximately from 2 to 25. Such spreading for b_{DSD} is not caused by the computation issues previously mentioned since it is visible on both b_{DSD} and b_{DSDfit} . This observed scattering, which is comparable regardless the estimation techniques and device, suggests that even if the power relation between *KE* and *R* remains relevant for all events, its parameters exhibit strong variability between events.

Figure 9: Variation of power law coefficients from UM and DSD calculation, for events in year 2019 (similar variation for other years also)



The constants of the power law relations (in literature) between KE and R are not universal in application and need tweaking as per the rainfall type, measurement location as well as techniques. Based on assumed dependence between DSD parameters and rain rate in formulation exponents; Salles et al. (2002) suggest four range of values for exponent values of the universal power law, and Uijlenhoet and Stricker (1999) propose six differ-

ent relationships in their research. Hence, in order to refine the analysis of this observed 602 variability between events and to examine possible dependence of a and b on type of rain, 603 events were sorted according to rain types. Table 4 shows, for Pars 1, averaged values of 604 gamma DSD parameters, indicator of the quality of the fitting, and power law coefficients 605 from both DSD and UM estimations across events sorted according to type of rainfall. Ta-606 bles for Pars 2 and PWS are given in appendix - (Table B1). For defining types of rainfall 607 from light to extreme, a classification based on intensity (Tokay and Short, 1996) was em-608 ployed. μ , λ and N_0 tend to decrease with heavier events, with a stronger trend for N_0 . 609 It should be mentioned that an opposite trend is reported in reference used; this could be 610 due to instrumental bias in DSD measurement as the impact disdrometer used in reference 611 is known to under-represents smaller drops in intense rainfall. It should also be noticed 612 that the capacity of the gamma distribution to model observed DSD diminishes with heav-613 ier rainfall (this is more visible on RMSE estimation over whole range of DSD and less 614 prominent in displayed estimate here involving only higher drop sizes), suggesting a limit 615 in validity for gamma distribution assumption. Also, an increase in mean diameter is no-616 ticed (not shown here). These findings are in agreement with previous studies reported in 617 literature (Carollo Francesco Giuseppe and Ferro Vito, 2015). When it comes to power law 618 coefficients, both a_{DSD} and b_{DSD} show increase with increasing rain rate, and this is more 619 pronounced for b_{DSD} . Given the observed decrease in validity of gamma distribution of 620 DSD, these trends should be taken carefully because they are likely to be mere artifacts and 621 not representative of the actual process at stake. In the case of UM estimated parameters, 622 b_{UM} follows similar trend with stronger magnitude (going from 8 to 33) while a_{UM} shows 623 slight reduction in value with increasing rain rate (from 1.25 to 1.05). Since the average 624 rainfall criteria used for classification here is a somehow arbitrary and more biased towards 625

lesser rainfalls, another classification relying on the maximum of 10 minute moving average was also employed. The results are tabulated in Table B2 (Appendix B). With this criteria which is more biased towards larger rainfall events, consistent and similar results are retrieved when it comes to values and variation of power law coefficients *a* and *b*, from DSD as well as UM, suggesting robustness of obtained trends.

			from UM								
		# events	# events μ		$\Lambda \mathbf{RMSE}_{DSD}$		a _{DSD}	b_{DSD}	a _{UM}	b_{UM}	
				$(m^{-3}mm^{-1-\mu})$	(mm^{-1})	$(m^{-3}mm^{-1})$		$(Jm^{-2}mm^{-a}h^{a-1})$		$(Jm^{-2}mm^{-a}h^{a-1})$	
very light	R < 1	188	2.53	1.05×10^{7}	6.34	19.32	1.196	11.056	1.253	8.554	
light	$1 \le R < 2$	173	1.75	1.71×10^{9}	4.81	24.53	1.222	12.694	1.224	9.334	
moderate	$2 \le R < 5$	141	1.01	2.51×10^{7}	3.42	21.25	1.256	15.580	1.214	10.216	
heavy	$5 \le R < 10$	36	0.44	1.40×10^{4}	2.25	20.45	1.275	17.259	1.210	11.336	
very heavy	$10 \le R < 20$	14	-0.05	1.17×10^{3}	1.63	21.14	1.300	18.419	1.119	19.670	
extreme	$R \ge 20$	4	-0.85	5.48×10^{2}	1.04	44.82	1.353	44.82	1.052	33.250	

Table 4: Variation of DSD parameters and power law coefficients according to the type of rainfall for Pars 1 (R = average rain rate for rainy time steps)

To evaluate the performance of established power law relationship across scales of 631 measurement, KE was calculated from empirical R using $KE = bR^a$ with average val-632 ues of a and b and compared with existing relations in literature. For this purpose, ex-633 ponential equation used in RUSLE ($KE_{BF} = 29[1 - 0.72\exp(-0.05R)]$, Brown and Fos-634 ter, 1987), exponential equation used in RUSLE2 ($KE_{MG} = 29[1 - 0.72\exp(-0.082R)]$, 635 C. McGregor et al., 1995), universal exponential law proposed by van Dijk et al. (2002) 636 $(KE_{VD} = 28.3[1 - 0.52\exp(-0.0421R)])$ and ideal power law proposed by Shin et al. 637 (2016) ($KE_{Shin} = 10.3R^{11/9}$) were used alongside KE_{UM} and KE_{DSD} derived here (power 638 law where fitted values of b were used $-KE_{DSD fit}$ - is also included). For UM and DSD 639 power laws in this paper, average values among all calculated events were used for repre-640 sentation according to make of disdrometers. Average values of coefficient a and prefactor 641 b were close for both Pars 1 and Pars 2 disdrometers and were taken common for the 642

Parsivel² make (for both UM and DSD). It is also logical to keep values of power law coef-643 ficients separate between different disdrometers as varying KE and R estimation has been 644 reported across types of disdrometers used (Angulo-Martínez and Barros, 2015; Angulo-645 Martínez et al., 2018; Johannsen et al., 2020b). Figure 10 shows KE and R variation fitted 646 with above mentioned equations for maximum resolution, 30 seconds. As expected KE_{UM} 647 provides better fit than KE_{DSD} (and $KE_{DSD fit}$ shows closer fits). With respect to empirical 648 data, UM power laws exhibit - for all three devices - slightly better or comparable coef-649 ficient of determination (r^2) with regards to commonly used relations. The exponential 650 equations from literature appear very close to each other. The relatively lower values of co-651 efficient of determination than that during event based fits are likely to be due to the effect 652 of using average values instead of event specific values of a and b. 653

Figure 10: Fitting of empirical KE - R using power laws from UM and DSD, and popular expressions from literature for a) and b) Parsivel², and c) PWS



To understand the performance of various equations further, r^2 was examined across various time periods and also across different type of rains. Results are displayed in Fig. 11. It appears that regardless of the duration as well as type of rainfall considered, tuned relations KE_{DSDfit} and KE_{UM} perform significantly better than the other fixed ones, yielding r^2 values greater than 0.9. In most cases, KE_{UM} exhibits slightly better performances with a difference not significant. The analysis also confirmed the poor performance of KE_{DSD} ,

i.e. the inability of the DSD approach to properly fit the prefactor 'b'. It should be stated 660 that the power law obtained using UM analysis is not providing significant performance en-661 hancement compared to that obtained from gamma DSD while the prefactor b is estimated 662 from fitting of the data (KE_{DSD fit}). However, with UM analysis, it is possible to discard 663 all assumptions of DSD following a gamma distribution thus eliminating the known inad-664 equacy of gamma model and its sensitivity to sampling resolution (Adirosi et al., 2013, 665 2014; Ignaccolo and De Michele, 2014; Adirosi et al., 2016; Gatidis et al., 2020). The in-666 adequacy was observed in current analysis as well, as previously discussed and illustrated 667 in Fig. 6 and Fig. 7. 668

Figure 11: r^2 values of various KE-R relations discussed for a) events analysed in 2017, 2018 and 2019 (for Pars 1),

b) all events grouped according to type of rain - light, moderate and heavy

Average value for each year is given in legends, with KE_{UM} and KE_{DSDfit} displayed in dotted lines



5. Conclusion

⁶⁷⁰ We examined the relationship between rainfall intensity R and time specific kinetic ⁶⁷¹ energy *KE* using high resolution (30 s) optical disdrometer data from the past 7 years in ⁶⁷² Paris region. The variability across scales of both parameters was characterized using the framework of Universal Multifractals. Analyzed *KE* and *R* times series were found to convey excellent multifractal behaviour (which is novel for *KE*), with multifractality index α and mean intermittency C_1 suggesting power law relation between them; it can be written as $KE = bR^a$. Such power law was found to be valid across analyzed data, i.e. independent of the event, on whether they are computed on event or yearly basis, and of the underlying corresponding drop size distribution. Some variability in the value of the exponent *a* and prefactor *b* is reported according the event and disdrometer type.

As shown by previous results, similar power-law can be theoretically obtained when 680 relying on the common assumption of a gamma distribution for the DSD, and a power-681 law relation between fall velocity and equivolumic drop diameter. KE-R relation obtained 682 through UM analysis was compared with results found using this common framework and 683 biases were acknowledged. Despite some exceptions, in most cases when a gamma DSD 684 approximation was relevant, estimations of power law parameters from the two approaches 685 were found to be consistent. When not, UM approach provided slightly better fit in general 686 but not in a significant manner, keeping in mind that the pre-factor needs to fitted to data in 687 both cases to ensure a fair comparison. Thus, the newly discussed power law relationship 688 between KE and R retrieved with the help of UM framework generalizes previous results 689 and theoretical formulations without having to rely on the ad-hoc assumption of a gamma 690 DSD. The main underlying assumption of UM framework, i.e. that there is an underlying 691 multiplicative process, is actually physically based in the sense that comes from the scale 692 invariance features of the Navier-Stockes equations. Here, a UM analysis confirmed the 693 validity of this assumption. Deriving the power-law relation in a multifractal framework 694 opens the path to new approaches for simulating KE from simple R measurements. Given 695 that complete KE measurement is much less available than R one, this impact will be 696

⁶⁹⁷ investigated further in future work.

⁶⁹⁸ For the future, it would hence be interesting to expand the data set across geographi-⁶⁹⁹ cal and meteorological conditions to reduce the biases that might have accumulated from ⁷⁰⁰ region of measurement.

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707 Appendix A: Multifractal events year wise



44

Appendix B: Method of moments

709 The formulation of moment estimator

Gamma distribution parameters were estimated from second, fourth and sixth momentsusing following relations:

713 M234:

$$D_m = M_4/M_3 \tag{B.1}$$

$$\eta = \frac{(M_3^2)}{(M_2 M_4)} \tag{B.2}$$

$$\mu = \frac{1}{(1 - \eta - 1)} - 4 \tag{B.3}$$

$$\Lambda = \frac{M_2}{M_3}(\mu + 3) \tag{B.4}$$

$$N_0 = \frac{M_2 \Lambda^{(\mu+3)}}{\Gamma(\mu+4)}$$
(B.5)

DSD parameters and power-law coefficients

					from UM						
			# events	μ	N_0	Λ	RMSE _{DSD}	a _{DSD}	b _{DSD}	a_{UM}	b_{UM}
					$(m^{-3}mm^{-1-\mu})$	(mm^{-1})	$(m^{-3}mm^{-1})$		$(Jm^{-2}mm^{-a}h^{a-1})$		$(Jm^{-2}mm^{-a}h^{a-1})$
	very light	R < 1	190	2.53	1.36×10^{7}	6.59	19.78	1.196	10.180	1.246	8.097
	light	$1 \le R < 2$	160	1.61	1.20×10^{8}	4.70	24.81	1.229	12.630	1.202	9.262
s 2	moderate	$2 \le R < 5$	101	0.82	1.66×10^{6}	3.19	20.93	1.260	15.026	1.208	9.911
Par	heavy	$5 \le R < 10$	28	0.26	2.72×10^{4}	2.14	23.85	1.281	17.171	1.247	10.140
	very heavy	$10 \le R < 20$	8	-0.38	5.81×10^{2}	1.36	21.20	1.317	19.951	1.098	19.997
	extreme	$R \ge 20$	6	-0.94	6.16×10^{2}	1.07	57.99	1.363	15.593	1.180	19.040
	very light	R < 1	163	2.79	7.82×10^{6}	4.73	10.95	1.187	10.95	1.194	12.070
	light	$1 \le R < 2$	176	2.65	2.64×10^{7}	4.15	14.30	1.195	14.30	1.154	12.703
VS	moderate	$2 \le R < 5$	152	1.87	4.73×10^{3}	2.85	14.98	1.216	20.024	1.169	13.136
ΡW	heavy	$5 \le R < 10$	46	1.16	2.82×10^{3}	1.96	18.90	1.253	24.439	1.193	13.933
	very heavy	$10 \le R < 20$	18	0.59	7.07×10^{2}	1.51	19.24	1.266	20.834	1.133	18.983
	extreme	$R \ge 20$	6	0.53	4.09×10^{2}	1.28	20.63	1.26	21.031	1.165	18.016

Table B1: Variation of DSD parameters and power law coefficients according to the type of rainfall (R = average of rainy data points)

				from UM							
			# events	μ	N_0	Λ	RMSE _{DSD}	a _{DSD}	b _{DSD}	a _{UM}	b_{UM}
					$(m^{-3}mm^{-1-\mu})$	(mm^{-1})	$(m^{-3}mm^{-1})$		$(Jm^{-2}mm^{-a}h^{a-1})$		$(Jm^{-2}mm^{-a}h^{a-1})$
	very light	R < 1	13	3.82	1.30×10^{7}	8.19	8.19	1.161	9.471	1.245	8.396
	light	$1 \le R < 2$	82	2.63	7.76×10^{6}	6.39	15.96	1.191	10.962	1.271	8.747
s 1	moderate	$2 \le R < 5$	235	2.04	1.10×10^{5}	5.32	21.77	1.213	12.528	1.227	9.119
Par	heavy	$5 \le R < 10$	134	1.44	2.22×10^{7}	4.19	24.79	1.235	13.826	1.225	9.369
	very heavy	$10 \le R < 20$	54	0.51	4.55×10^{3}	2.67	20.75	1.269	16.214	1.197	11.697
	extreme	$R \ge 20$	38	-0.22	1.77×10^{3}	1.67	26.84	1.314	26.84	1.147	16.642
	very light	R < 1	13	4.27	2.02×10^{7}	8.94	6.75	1.154	9.097	1.217	7.833
	light	$1 \le R < 2$	82	2.97	2.96×10^{6}	7.04	15.74	1.183	10.165	1.253	8.245
s 2	moderate	$2 \le R < 5$	215	1.99	9.38×10^{7}	5.43	22.15	1.214	11.857	1.212	8.810
Par	heavy	$5 \le R < 10$	112	1.17	3.20×10^{6}	3.94	24.33	1.239	12.969	1.222	9.280
	very heavy	$10 \le R < 20$	42	0.39	5.92×10^{3}	2.74	25.49	1.276	15.369	1.196	10.696
	extreme	$R \ge 20$	29	-0.63	1.78×10^{3}	1.55	35.88	1.343	18.133	1.192	13.445
	very light	R < 1	6	3.84	3.39×10^{4}	6.15	6.78	1.16	13.92	1.223	13.322
	light	$1 \le R < 2$	61	3.26	5.29×10^{4}	5.27	10.13	1.175	14.687	1.187	11.997
VS	moderate	$2 \le R < 5$	201	2.59	1.91×10^{7}	4.20	12.56	1.195	17.258	1.176	12.602
Μ	heavy	$5 \le R < 10$	168	2.32	2.78×10^{6}	3.50	14.65	1.202	19.013	1.168	12.702
	very heavy	$10 \le R < 20$	75	1.72	3.31×10^{3}	2.65	16.90	1.223	20.846	1.155	14.401
	extreme	$R \ge 20$	50	0.67	1.11×10^{3}	1.69	19.48	1.264	20.879	1.156	15.430

Table B2: Variation of DSD parameters and power law coefficients according to the type of rainfall (R = maximum value of 10 minute moving average)

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