

Multifractal characterisation of a simulated surface flow: A case study with Multi-Hydro in Jouy-en-Josas, France

Auguste Gires, Jean-Baptiste Abbes, Igor da Silva Rocha Paz, Ioulia Tchiguirinskaia, D Schertzer

► To cite this version:

Auguste Gires, Jean-Baptiste Abbes, Igor da Silva Rocha Paz, Ioulia Tchiguirinskaia, D Schertzer. Multifractal characterisation of a simulated surface flow: A case study with Multi-Hydro in Jouy-en-Josas, France. Journal of Hydrology, 2018, 558, pp.482 - 495. 10.1016/j.jhydrol.2018.01.062 . hal-01704091

HAL Id: hal-01704091 https://enpc.hal.science/hal-01704091v1

Submitted on 8 Feb 2018

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers. L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

1	Multifractal characterisation of a simulated surface flow: a case study with
2	Multi-Hydro in Jouy-en-Josas, France
3	Auguste Gires ^{*1} , Jean-Baptiste Abbes ¹ , Igor da Silva Rocha Paz ^{1,2} , Ioulia Tchiguirinskaia ¹ ,
4	Daniel Schertzer ¹
5	1. HMCO, École des Ponts ParisTech, U. Paris-Est, Champs-sur-Marne, France,
6	2. Instituto Militar de Engenharia, Rio de Janeiro, Brazil
7	* Corresponding author: Auguste Gires, <u>auguste.gires@enpc.fr</u> (phone +33 1 64 15 36 48; fax
8	+33 1 64 15 37 64)
9	
10	Abstract
11	In this paper we suggest to innovatively use scaling laws and more specifically
12	Universal Multifractals (UM) to analyse simulated surface runoff and compare the retrieved
13	scaling features with the rainfall ones. The methodology is tested on a 3 km ² semi-urbanised
14	with a steep slope study area located in the Paris area along the Bièvre River. First Multi-
15	Hydro, a fully distributed model is validated on this catchment for four rainfall events
16	measured with the help of a C-band radar. The uncertainty associated with small scale
17	unmeasured rainfall, i.e. occurring below the 1km x 1km x 5min observation scale, is
18	quantified with the help of stochastic downscaled rainfall fields. It is rather significant for
19	simulated flow and more limited on overland water depth for these rainfall events. Overland
20	depth is found to exhibit a scaling behaviour over small scales (10 m - 80 m) which can be
21	related to fractal features of the sewer network. No direct and obvious dependency between
22	the overland depth multifractal features (quality of the scaling and UM parameters) and the
23	rainfall ones was found.

25 1) Introduction

26

27 The combined effects of a growing urbanisation - approximately 80% of Europe's 28 population will live in cities by 2020 (EEA, 2014) - and potential increase of extreme events 29 as a consequence of climate change (IPCC, 2013) expose more and more people to surface 30 pluvial flooding. Pitt (2008) carried out a review on flood events in the United Kingdom and 31 showed that two thirds of the flood related damages were caused by surface water flooding. Urban flooding has become a growing concern in Europe, hence a significant number of 32 33 European research projects address this issue, along with national counterparts. The purpose 34 of these projects is to increase the resilience of urban areas through improvement of both real 35 time management of extreme events and long term planning. We can cite FP7 SMARTesT 36 (http://floodresilience.eu/), CORFU (http://www.corfu-fp7.eu/), Climate KIC Blue Green 37 Dream (www.bgd.org.uk) or the INTERREG IV RainGain project (http://www.raingain.eu) 38 among others. 39 There is a need to improve the understanding of urban surface flow. Indeed, there is a

40 growing interest for 2D models in urban environment for both operational and research 41 applications (Bolle et al., 2006; Carr and Smith, 2006; Chen et al., 2007; Deltares, 2013; DHI, 42 2011; Giangola-Murzyn et al., 2014; Innovyze, 2012, 2103; Phillips et al., 2005; XP 43 Solutions, 2012). Such models aim at actually modelling processes in a physically based 44 manner, while the most commonly used semi-distributed models take them into account 45 through tailored lumped models. In case of overflow they simply consider a volume output 46 from the sewer system and deduce a local water depth, but the dynamical behaviour of the 47 water added on the ground is not addressed. Basically, urban surface flow is not commonly 48 perceived as a geophysical process and is therefore not addressed with geophysical tools

49 capable of grasping its intrinsic complexity visible across all scales. Indeed, it results from the 50 non-linear interactions between the highly spatially and temporally variable rainfall field, the 51 topography and the strongly inhomogeneous land use cover.

52 In this paper we suggest to use multifractal tools, which are commonly used in 53 geophysics to characterise and simulate fields extremely variable over a wide range of scales; 54 such as wind turbulence, rainfall, river flow or topography (see Schertzer and Lovejoy, 2011 55 for review). Such tools have seldom been used in an urban context. Gires et al. (2013, 2014b) 56 used them to downscale rainfall to quantify the uncertainty associated with small scale rainfall variability, or to characterise the variability across scales of simulated flow in conduits 57 58 (sewer). To the knowledge of the authors it has never been used to study either surface runoff 59 flow (urban drainage) or surface flow in general including stream rivers. Investigating the 60 potential multifractal features of surface flow and notably whether it inherits rainfall features 61 is the main purpose of this paper and constitute its main novelty. In addition, this case study 62 will also be used to quantify the uncertainty associated with small scale rainfall variability, not only on the simulated flow which has already been done on other catchments, but also on 63 64 the surface flow.

Given the lack of measurements of distributed data of surface runoff, outputs of a 65 numerical model are analysed. The model used is Multi-Hydro (El Tabach et al., 2009 for an 66 67 initial version and Giangola-Murzyn, 2014 for a recent one) developed at the Ecole des Ponts 68 ParisTech. It is implemented on a 3.017 km² peri-urban catchment in Jouy-en-Josas (South-East of Paris), which exhibits steep slopes and both forest and urbanised areas. Achieving 69 70 such an analysis is relevant only if a distributed rainfall field is used as model input. Météo-71 France radar mosaics with a resolution of 1 km in space and 5 min time (Tabary, 2007; 72 Tabary et al., 2007) for four events that occurred between 2009 and 2011 are used. When

73	needed, the rainfall field is downscaled both in space and time from the raw radar data, in
74	order to simulate the improvement that could be made with higher radar resolution.
75	The model and the study area data for its implementation are presented in details in
76	section 2. The multifractal framework and analysis methods are presented in section 3.
77	Results are discussed in section 4 and 5. More precisely, the validation of the model and
78	quantification of the uncertainty associated with small scale unmeasured rainfall variability on
79	both simulated sewer flow and maximum water depth is carried out in section 4. Multifractal
80	characterization of overland water depth is addressed in section 5. Main conclusions are
81	highlighted in section 6.
82	
83	
84	2) Model and catchment
85	
86	2.1) The Multi-Hydro model
87	
88	Multi-Hydro is a multi-module model whose goal is to model and predict the impacts
89	of rainfall events in urban and peri-urban areas. In this paper, there is an emphasis on heavy
90	rainfall events. Following the approach of various recent developments of hydrological
91	models (Djordjevic et al., 1999; Fletcher et al., 2013; Hsu et al., 2000; Jankowfsky, 2011;
92	Rodriguez et al., 2008); it makes different modules interact, each of them echoing a portion of
93	the water cycle in urban areas (surface runoff, infiltration, ground water flow, sewer flow).
94	Each of the modules integrated in Multi-Hydro relies on open-source software
95	packages that have already been widely used and validated by the scientific community. The
96	surface module is based on TREX (Two dimensional Runoff, Erosion and eXport model,
97	Velleux et al., 2011) which solves fluid mechanics equations for surface flow (diffusive wave

98 approximation of 2D Saint-Venant, see p. 6-7 of the TREX user manual) and infiltration 99 (simplification of Green and Ampt equation). The sewer or drainage module, which is based 100 on SWMM developed by the US Environmental Agency (Storm Water Management Model, 101 Rossman, 2010), is a 1D-model dealing with sewer flows through numerical solutions of 102 Saint-Venant 1D equations in pipes. The interactions between the surface and sewer flow is 103 handled through the gully pixels. These interactions (input or output of water) between the 104 surface and sewer flow are carried out every 3 min. When there is no overflow, gully pixels 105 are considered to have an infinite infiltration rate, and the water passing through them is 106 directly inputted into the corresponding node of the sewer model. This way of modelling 107 implies that a large transport capacity is assumed for gully, especially with 10 m pixel size as 108 in this paper (see below). Future developments of Multi-Hydro will enable to improve the 109 model with regards to this coarse assumption. They could notably rely on the experimental 110 and computational studies of gully inflow capacity, including 3D CFD studies, which analyse 111 phases in the flow, inlet capacity, reverse flow when the piezometric level in the sewer is 112 beyond the ground level (Despotovic et al., 2005; Djorjevic et al., 2005). In case of sewer 113 overflow through a node, the corresponding gully pixel is converted into a road pixel and the 114 water exiting the node is inputted on this pixel (considered as a source in TREX). There is 115 also a module handling ground water flow which was not included in this study to limit 116 computation time.

In order to run Multi-Hydro, data needs to be shaped in a standard format. Commonly available Geographical Information System (GIS) data, such as land use and topography provided in France by IGN (the French agency producing geographical information) are inputted to MH-AssimTool (Richard et al., 2014). This software formats the inputs with the desired resolution and makes Multi-Hydro a transportable model, rather easy to implement on a new catchment. Once a resolution is chosen, one has to affect an elevation and a land use

123 class to each pixel. The elevation is obtained by an interpolation of the raw available data.
124 With regards to the land use, a priority order has been determined to assign a unique land use
125 class for a given pixel according to the hydrological importance of the given class instead of
126 the surface represented by this class: if a gully is located on a pixel, the entire pixel will be
127 considered as a gully. This process is repeated in the following order for this case study:
128 roads, houses, forest, grass, and water surface. See Ichiba et al. (2017) for a comparison with
129 other possible strategies.

130 In this paper, the model was implemented with pixels of size 10 m x 10 m. Given the 131 obtained results discussed below it was not found necessary to run it at higher resolution 132 which makes computation time too long. For an in-depth analysis of the relation between the 133 selected pixel size and simulated flow, which is not the purpose of this paper, refer to Ichiba 134 (2016). Multi-hydro was not calibrated, i.e. standard values for the parameters describing a 135 land use class are used (hydraulic conductivity, capillary suction, moisture deficit, Manning's 136 coefficient, depth of interception). Raw or downscaled radar data are used as input of the 137 model.

138

139 2.2) Presentation of the study area

140

The catchment studied in this article is located in Jouy-en-Josas (Yvelines County, South-west of Paris). It occupies a 3.017 km² area, mainly on the left bank of the Bièvre River. A small portion of the right bank near the river bed is also included. The remaining portion of the right bank is drained to a small river that flows into the Bièvre River downstream the outlet of the studied catchment. The Bièvre River is a tributary of the Seine River which it meets in Paris. It flows through increasingly urbanised areas along its 33 km path. This has led to strongly modify its natural bed, both in underground pipes which are

integrated in the storm water sewer system, or in a highly artificial open air bed. An effort iscurrently undertaken to restore its "natural" aspect.

150 A striking feature of this catchment is that, unlike the previous ones studied with 151 Multi-Hydro (Giangola-Murzyn et al., 2014; Gires et al., 2014a), it exhibits steep slopes. 152 There is a difference of approximately 100 m between the plateau in the north of the 153 catchment, and the outlet of the catchment (Fig. 1). The downhill portion strengthens overland 154 runoff, and the combination of pluvial and fluvial processes on the river bank has led to 155 severe flooding in 1973 and 1982. Some details are available on the SIAVB (Syndicat 156 Intercommunal d'Assainissement de la Vallée de la Bièvre, the local authority in charge of 157 urban drainage of the area) website http://www.siavb.fr/gestion_des_crues.aspx. Urbanisation 158 and imperviousness are concentrated along the river bank, and on a housing estate along one 159 major North-South road. The remaining of this semi-urban catchment is mainly made of 160 forests. The sewer system is a separate one, and the storm water is routed into the Bièvre 161 River.

162 Following the severe flooding, the SIAVB has created 15 storage basins (integrated in 163 the landscape) along the Bièvre River to mitigate flooding risks. One, the Bassin des Bas Près, 164 is located just upstream the Jouy-en-Josas catchment. The outlet of this basin is equipped with 165 flow and height gauges operated in real time. There is a second measuring point of water 166 depth, few meters upstream the outlet of the catchment, at the "Pont de Pierre" (Fig. 1). This 167 gauge has been installed to monitor the river level and to protect a music school by triggering 168 a warning system in case of elevated height. Given the position of the two measuring points, 169 Multi-hydro will only be validated on the area drained by the sewer network represented in 170 green in Fig. 1. The forest corresponds approximately to 60% of the catchment (~ 2 km^2). 171 Although it is only possible to validate the implementation of the model on a portion of the 172 catchment, the whole area is modelled to ensure the accuracy of flow over the areas actually

used for validation. The river is part of the storm water sewer system in Jouy-en-Josas and is
modelled as a pipe in Multi-Hydro drainage module. Indeed, through the city, the river bed is
highly artificial or even underground. The long and West – East oriented pipe located in the
South of the Basin (Fig. 1, left) is actually the Bièvre River.

177

178 2.3) Fractal dimensions of the impervious surfaces and of the sewer system

179

180 The studied catchment is located in a semi-urbanised area. The impervious surfaces 181 are highly relevant for hydrology since they basically correspond to areas where runoff is 182 quickly active during a storm event. Thanks to the determination of land use per pixel in MH-183 AssimTool, the evaluation of the impervious areas can be done in an apparent simple way by 184 calculating the number of pixels of roads, buildings and gullies (since the water falling on 185 gully pixels is immediately routed to the sewer network, they are considered as impervious). 186 This impervious surface depends on the resolution at which it is computed. Indeed, an 187 imperviousness of 55%, 50%, 42%, 32% and 25% is obtained with pixels of size 20, 15, 10, 188 5, 2 m respectively. This is due to the priority order set in the data assimilation tool that 189 affects a land use for each pixel. This order prioritizes impervious areas (Fig. 2). Obviously 190 these values strongly depend on the approach implemented to affect a land use class to a 191 pixel. As previously mentioned, comparison with other approaches can be found in Ichiba et 192 al. (2017). Investigations on the possibility of having different pixel size according to the land 193 use should also be envisaged in the future, in order to for instance refine the pixels for roads 194 and gullies and coarser them for forests. Coming back to the imperviousness percentages 195 found in this paper, it is possible to use the notion of fractal dimension, which is scale 196 invariant, to explain these figures. The fractal dimension $D_{\rm F}$ of a geometrical set (here the 197 impervious pixels) is obtained with the help of the following equation:

198 $N_{\lambda} \approx \lambda^{D_F}$ Eq. 1

199 where N_{λ} is the number of impervious pixels, and λ is the resolution defined as the ratio

between the outer scale *L* of the phenomenon and the observation scale $l (\lambda = \frac{L}{l})$. It characterizes the space occupied by a geometrical set in a scale invariant way. The symbol \approx denotes an asymptotic convergence and absorbs slowly varying prefactors.

203 For the studied catchment, it appears that the impervious areas exhibit a fractal 204 dimension. Indeed Eq. 1 is plotted in log-log for the geometrical set consisting of the 205 impervious pixels at the 2-m resolution (imperviousness of 25 %), and a straight line is 206 retrieved on the whole range of scales, i.e. 2m-2048m (Fig. 3.a). This a basic feature of the 207 catchment. The fact that the points corresponding to the catchment representation at 20, 15, 208 10, 5, 2 m obtained with MH-AssimTool are along this straight line (circled cross on Fig. 3.a) 209 is simply a consequence of the priority order set for affecting a land use class to a pixel 210 (impervious classes are prioritised over pervious ones). This confirms the fact that even though the represented imperviousness varies with scale, a feature (the fractal dimension) is 211 212 conserved and provides a quantification of the level of urbanisation. We find $D_{\rm F}$ equal to 1.73 213 for this catchment. In a previous study Gires et al. (2014a), found that for a highly urbanised 214 area in Seine-Saint-Denis (North-East of Paris), the fractal dimension was of 1.85 from on 215 scales ranging from 1 m to 1024 m. Given that this catchment is less urbanised, it was 216 expected to obtain a smaller fractal dimension.

The same study was performed on the sewer system (Fig. 3.b). In this case, the geometrical set studied is the "rasterised" sewer system. If a pixel is crossed by a conduit belonging to the storm water sewer network, then it is considered as part of the sewer system.. Two scaling regimes can be identified: from 10 m to 80 m the fractal dimension is 1.03 and from 80 m to 1280 m it is 1.76. For small scales, the dimension is close to 1, and it simply reflects the 1D intrinsic nature of the sewer system. For large scales, the structure of the network becomes apparent, and exhibits a scaling behaviour. For large scales the value is
slightly smaller than the 1.85 found on the Seine-Saint-Denis catchment in Gires et al.
(2014a) which is consistent with the fact that this one is less urbanised. The similarity
between both fractal dimensions (imperviousness and large scale sewers) indicates that it is a
relevant way of quantifying a level of urbanisation for the area. See Gires et al. (2017) for an
extension of this approach to 10 areas in 5 European countries.

229

230 2.4) Rainfall data

231

232 Four rainfall events, which occurred between 2009 and 2011, are studied in this paper. 233 Simulations are performed using Météo-France radar mosaic, which provides a spatially 234 distributed data with a resolution of 1 km x 1 km x 5 min (the closest radar is the C-band one 235 of Trappes located 15 km West). For three events the data recorded with the help of a rain 236 gauge operated by the SIAVB located a few hundred meters south of the catchment at the 237 "Bassin des Bas Près" is also available. Because of (i) the standard 0.2 mm discretization issue of the tipping bucket rain gauge (data is number of tips equal to 0.2 mm) which prevents 238 239 it from providing reliable intensity, (ii) the gap between the observation scales of the two 240 measuring devices (see Gires et al., 2014b, for an in-depth analysis of this issue) and (iii) the 241 fact that the rain gauge is furthermore outside of the catchment; it is not possible to use the 242 rain gauge data for other purpose than a rough check of the accuracy of radar data. It is done 243 by comparing the cumulative volumes of rainfall for each studied event which are displayed 244 in Table 1 along with their main features. Gires et al. (2014b) used data from dense network of point measurement devices (rain gauges or disdrometers) distributed over 1 km^2 and 245 246 showed that the cumulative depth differences between devices could reach more than 40 % 247 for individual rainfall events (of the same order of magnitude as the one discussed here). They 248 showed with the help of numerical simulations that similar values were found simply taking 249 into account small scale rainfall variability. Here the maximum observed differences are 34%, 250 which suggests that the agreement between the two devices is acceptable, i.e. smaller than 251 expected uncertainty simply due to the scale gap between the two measuring devices. Authors 252 did not have access to longer time series of both radar and rain gauge to perform a more in-253 depth evaluation of the radar versus rain gauge measurement for this specific point, which 254 would be the topic of another study. The temporal evolutions of the radar rain rate averaged 255 over the catchment are displayed in Fig. 4. These events were selected because they are heavy 256 ones. However they are not extreme ones, indeed over durations of 1 h and 4 h, only the 14 257 July 2010 event has a return period greater than 1 year (data from a rain gauge located in the 258 Paris area that was available to the authors was used to obtain these estimates). For the July 259 event, the return period is of about 1 year for a duration of 1 h and of about 2 years for a 260 duration of 4 h.

261

262 3) Methods

263 3.1) Multifractal framework

264 The Multifractal framework is used for several purposes throughout this paper to 265 characterize the variability across scales of fields, and is therefore presented here in a generic 266 way. Only basic properties are discussed here, and interested readers are referred to the recent 267 review by Schertzer and Lovejoy (2011) for more details. The general assumption of 268 multifractal fields is that they are generated by an underlying scale invariant multiplicative 269 cascade process. In such process, a structure at a given scale is divided into smaller structures 270 at smaller scale and the value of a child structure is equal to the value of the parent structure 271 multiplied of a random increment. The process is scale invariant in the sense that the way 272 structures are divided into sub-structures and the probability distribution of the random

multiplicative increments are the same at all scales. A consequence is that statistical properties of such fields are conserved across scales. More precisely let us denote ε_{λ} a field at resolution λ (=*L*/*l*, where *l* is the observation scale and *L* the outer scale of the phenomenon as for the fractal dimension definition). The probability of exceeding a given threshold (λ^{γ}), defined with the help of the scale invariant notion of singularity γ (the thresholds depend on the observation scale, but not the singularity),

- 279 $\Pr(\varepsilon_{\lambda} \ge \lambda^{\gamma}) \approx \lambda^{-c(\gamma)}$ Eq. 2,
- and the moment of order q,
- 281 $\left\langle \varepsilon_{\lambda}^{q} \right\rangle \approx \lambda^{K(q)}$ Eq. 3,

282 exhibit a power law relation with regards to the resolution at which they are computed. As for 283 Eq. 1, the symbol \approx denotes an asymptotic convergence and absorbs slowly varying 284 prefactors. Equations 2 and 3 define respectively the codimension function $c(\gamma)$ and the 285 moment scaling function K(q), which both fully characterize the variability across scales of 286 the field. $c(\gamma)$ and K(q) contain the same information and are related by a Legendre transform 287 (Parisi and Frish, 1985). Eq. 2 can be understood from the simpler notion of fractal dimension (Eq. 1). Indeed, an intuitive interpretation of a multifractal field is that the geometrical sets 288 289 made of each portion of the field greater than given thresholds are fractal and characterized by 290 fractal dimensions. To be mathematically more rigorous the notion of threshold is replaced by 291 the scale invariant one of singularity.

By generalizing the central limit theorem Schertzer and Lovejoy (1987) showed that any conservative scale-invariant multiplicative processes converge toward Universal Multifractals (in a similar way as re-normalized sum of identical and independent random variables converge toward normal distribution as long as their variance is defined). For Universal Multifractals (UM), i.e. this limit behaviour, K(q) and $c(\gamma)$ functions are defined

297	with the help of only two relevant parameters with a physical interpretation. They are known							
298	as UM parameters C_1 and α :							
299	- C_1 is the mean intermittency which measures the average sparseness of the field. $C_1=0$ for a							
300	homogeneous field.							
301	- α is the multifractality index ($0 \le \alpha \le 2$) and measures how fast the intermittency evolves							
302	when considering level of activity slightly different from the average one.							
303	Great values of α and C_1 corresponds to strong extreme. A common tool to assess the							
304	extremes of a field is the scale invariant notion of maximum probable singularity γ_s							
305	observable (Hubert et al., 1993; Douglas and Barros, 2003; Royer et al., 2008; Gires et al.,							
306	2014a). It is defined for a unique sample by							
307	$c(\gamma_s) = d$ Eq. 4							
308	Where <i>d</i> is the dimension of the embedding space, i.e. $d = 1$ for time series and $d = 2$ for							
309	maps.							
310	The power spectrum (Fourrier transform of the auto-correlation function) of such							
311	multifractal field exhibits a scaling relation with wave number k:							
312	$E(k) \approx k^{-\beta}$ Eq. 5							
313	where β is the spectral slope.							
314								
315	3.2) Uncertainty associated with small scale rainfall							
316	The purpose of this section is to explain the approach implemented to quantify the							
317	uncertainty associated with small scales rainfall variability, i.e. which is occurring below the 1							
318	km x 5 min scale currently provided by the C-band radar operating in this area. The same							
319	methodology as in Gires et al. (2013, 2014a) is implemented, and only basic ideas are							

- 320 explained here. Firstly, an ensemble of downscaled rainfall fields is generated, then each
- 321 realisation is inputted into the numerical model and finally the disparities within the ensemble

of outputs, which reflect the studied uncertainty, are analysed and quantified. 100 sample
ensembles are used. The downscaling technique relies on the Universal Multifractal
framework. It basically consists in stochastically continuing a space-time cascade process that
has been validated on the available range of scales. The resolution of the downscaled rainfall
field is 12 m in space and 20 s in time starting from the original 1 km and 5 min of the
available radar data. The process has been validated down to such small scales (Gires et al.,
2014b).

The disparities among the simulated ensembles are quantified with the help of quantile analysis. Let us first illustrate this with the flow output, but the same is done for maximum water depth at each pixel. For each time step the 5, 25, 75 and 95 % quantiles are computed, and give the envelop curves $Q_{0.05}$, $Q_{0.25}$, $Q_{0.75}$, and $Q_{0.95}$, respectively. The width between these curves characterizes the uncertainty interval on simulated flow. It is quantified with the help of two pseudo-coefficients of variation computed as:

335
$$CV_{95}' = \frac{Q_{0.95}(t_{PF,radar}) - Q_{0.05}(t_{PF,radar})}{2*PF_{radar}}$$
 Eq 6.a

336
$$CV_{75}' = \frac{Q_{0.75}(t_{PF,radar}) - Q_{0.25}(t_{PF,radar})}{2*PF_{radar}}$$
 Eq 6.b

337 where t_{PF} , radar is the time of the peak flow simulated with the raw radar data 338 (PF_{radar})..

339

340 3.3) Multifractal analysis of overland water depth maps

There is no distributed data available for overland water depth over large areas, but it is possible to study the fields obtained with the help of numerical simulations with spatially distributed rainfall as input. Maps of water depth during runoff at the end of each 3 min Multi-Hydro loop are studied.

345	Technically, in this paper an area of 128 x 128 pixels of size 10 m x 10 m is extracted
346	from the map of the catchment to carry out the analysis. Both ensemble analysis (i.e.
347	considering all successive maps as independent realisations of the same process and upscaling
348	them individually before taking the mean in Eq. 2 and 3) and individual time step analysis
349	(i.e. to obtain temporal evolutions of the various parameters) are performed. Finally, analyses
350	are done in 2D on the maps but also in 1D on the columns or the lines of pixels over the
351	catchment, in a North-South direction and in an East-West direction respectively (Fig. 5). The
352	purpose of this is to monitor a possible influence of the slope over the generated runoff
353	scaling properties.
354	
355	
356	4) Implementation of the Multi-Hydro model on the Jouy-en-Josas catchment
357	
358	4.1) Validation with raw radar data
359	
360	The validation of the model is achieved by comparing the water height measured at the
361	Pont-de-Pierre gauge with the simulated one. Before going on authors would like to highlight
362	that a proper validation on this case study is not possible given the available data, and will
363	therefore limit this section to checking that the model approximately behaves well. The main
364	reasons for this problem are:
365	- Only one measuring point is available for the whole catchment taking into account
366	approximately an area of 2 km^2 .
367	- The uncertainty associated with this water level gauge is high. Indeed, it is not operated for
368	accurate hydraulic measurement but to trigger an alarm to evacuate a music school located
369	nearby. The main issue is that the shape of the river bed cross section at this point is not

available. The width was estimated at around 1.80 m, using aerial photography from IGN and
an approximate measure from few meters away. In order to correctly model the pipe, we used
Multi-Hydro and tested various types of conduits. Finally, we chose to model the Bièvre as a
circular pipe, with free surface of 2 m diameter, which is close to the approximate
measurement. This choice is only an approximation which does not take into account the
variations in time of this shape due the fact that the bottom of the river bed is not flat and
contains moving rocks and changing vegetation.

377 - There is a lack of available data on initial soil saturation which is one of main sources of 378 uncertainty and can biased runoff (see Shah et al., 1996; Zehe et al., 2005) especially at the 379 beginning of the event. In this paper, dry conditions were considered at the beginning of each 380 event. A sensitivity test was conducted by considering a saturated soil at the beginning. A 381 slight increase (few percent) of simulated flow was noted only during approximately the first 382 hour (not shown here). Having longer rainfall time series would enable to simulate the 383 catchment's behaviour some time before the event and limit the uncertainties associated with 384 this issue.

- The uncertainties on the water input in the Bièvre River at the outlet the Bas-Près storage
basin upstream the catchment are not quantified.

- Obviously there are some uncertainties on the radar rainfall measurement itself.

388 The simulation and measurement at the "Pont de Pierre" point for the selected rainfall 389 events are displayed in Fig. 6. For the 09-02-2009 event we observe a clear overestimation at 390 the beginning of the event. For the 14-07-2010 event Multi-Hydro with the radar rainfall data 391 reproduces well the two main peaks, but overestimates the first local maximum of rainfall 392 intensity and misses the second one. The 15-08-2010 event shows a greater variability in the 393 first half of the simulation (variations are more pronounced on the model than on the 394 measurements) but reproduces well the last peak. Finally, for the 15-12-2011 event, the Multi-

Hydro model reproduces well the first peak, but the flow decreases more rapidly than theobservations.

397 Given the available data on a limited number of events it is difficult to attribute the 398 observed discrepancies to one or several of the previously mentioned sources of uncertainty. 399 Proper validation would indeed require the analysis of much longer time series and more 400 accurate measurements with better position of sensors. Nevertheless, the obtained results do 401 not highlight strikingly wrong behaviour of simulated water heights in conduit, and enable to 402 partially reproduce observations. Finally, it seems that for some events the simulated flows 403 might be too noisy compared with observed water levels. This should not affect the UM 404 analysis that follows because the analyses carried out in this paper are spatial ones, i.e. maps 405 are studied and not time series so the potential effect should be limited. Keeping in mind the 406 previously mentioned limitations, results suggest that it remains relevant to use this 407 implementation of Multi-Hydro with a rather coarse 10 m resolution for testing its sensitivity 408 to small scale rainfall variability and analysing surface runoff with the help of multifractals. The authors acknowledge that further investigations on other catchments with more 409 410 accurately validated models would be needed to fully confirm the findings discussed after.

411

412 4.2) Uncertainty associated with small scales rainfall variability

The envelop curves $Q_{0.05}$, $Q_{0.25}$, $Q_{0.75}$, and $Q_{0.95}$ are displayed in Fig. 7 for the 09-02-2009 event for 5 conduits selected from upstream to downstream, which enables to analyse the effect of the position of the conduit within the network. Link #4 corresponds to the Pontde-Pierre measurement, and #5 to the outlet of the catchment. As it can be seen in Fig. 7, link #4 and #5 are located along the Bièvre River, and they take into account the significant base flow in the river coming from upstream the Jouy-en-Josas catchment. It means that they are obviously less sensitive to local rainfall variability. Similar curves were also generated for water height (not shown) at the Pont-de-Pierre. The computed uncertainty is small and
certainly does not explain the discrepancies between simulations and measurements noticed in
Fig. 6, which are hence not simply due to effects of small scale rainfall variability.

423 CV'_{95} and CV'_{75} values computed for the selected conduits (Fig. 7) and the four events 424 are displayed in Table 2. As expected they decrease while considering more and more 425 downstream conduits. There is a sharp decrease in CV' when the Bièvre River is reached 426 because the base flow of the river dampens the effect of local small scale rainfall variability 427 occurring over the 3 km² catchment, but the uncertainty only associated with this effect 428 remains of roughly 10 % at the outlet whatever the event. The values for up-stream and mid-429 stream pipes are great for all events, even for CV'_{75} which highlights a significant impact of 430 small scale rainfall variability on the simulated flow. The variability observed in the simulated 431 flow is basically due to the disparities in the simulated downscaled rainfall fields which are 432 transferred through the hydrological model (see Gires et al. 2012 for more detailed analysis of 433 this issue). Small scale rainfall data is needed to understand better, and plan better, some local 434 flooding due to sewer overflows which have been reported in some areas, notably the street 435 parallel to the Bièvre River bed in the city (just North of it), There does not seem to have a 436 straightforward relation between the computed uncertainty and the strength of the event (in terms of maximum rainfall peak intensity over 5 min). Indeed, the tendency that could be 437 438 observed on the 09-02-2010, 15-08-2010 and 15-12-2011 (not a linear one as for example the peak rainfalls are equal to approximately 7 and 24 mm.h⁻¹ for respectively the 15-08-2010 and 439 440 15-12-2011 event while the computed uncertainties are close) is not confirmed by the results 441 for the 14-07-2010 event (see Tab. 2). Finally, these values are comparable to the ones that were obtained on a 1.5 km² highly urbanised catchment located 40 Km North-East on the 442 other side of the Paris area in Gires et al. (2014a). For this catchment, CV'_{95} values were 443 444 ranging from 21 to 56%, 26 to 94% and 22 to 50% from downstream to upstream for the same

445 09-02-2009, 15-08-2010 and 15-12-2011 events respectively (at a different location). The
446 values are slightly smaller for this catchment and this is likely to be due to lower level of
447 imperviousness resulting in a smaller portion of rainfall becoming immediately active.

448

449 In this paper, the uncertainty is computed not only on the simulated flow, but also on 450 the water depth in streets. As for the flow, for each realisation of downscaled rainfall field, the 451 maximum water depth over the whole simulation is retrieved for each pixel. A sample is 452 shown in Fig. 8.a for the 15-12-2011 event. The known hot spots are visible, although with 453 too high values. For example, the modelled maximum water depth reaches more than 15 cm 454 in the street along the Bièvre River bank in the city and the parallel street just north of it 455 (already mentioned in the previous paragraph). Although some flooding is regularly reported 456 by citizens to the SIAVB for these streets, such height was not reported for this event. In the 457 urbanized portion of the catchment the street network is visible on the maximum water depth 458 map, meaning the maximum values of water depth maps are reached on the corresponding 459 pixels. Lower values are found on the on roads/streets located on the steep portion of the 460 catchment because water moves faster in these areas. Same patterns and numerical values are 461 obtained for other realisations of the same event. Similar plots are obtained for the other 462 events with lower depths for the 09-02-2009 and 15-08-2010 (for which a lower cumulative 463 rainfall depth was recorded) and greater depths for the 14-07-2010 event. Then, as for the 464 flow analysis previously carried out, the uncertainty on this maximum water depth is 465 computed with the help of the 5 and 95% quantiles for each pixel and a pseudo-coefficient of 466 variation. Illustrations of the quantiles maps are shown in Fig. 8.b and 8.c for the 15-12-2011 467 event. Similar patterns are observed on the two maps, notably for the hotspots previously 468 mentioned which are visible on both maps. Maps of CV'₉₅ for maximum depth are displayed 469 in Fig. 9 for the four rainfall events. It appears that the uncertainty is lower for the areas

470 where the greatest maximum depths are found (i.e. on roads) and is also lower for the heaviest 471 rainfall events. It reaches only few percents on the hottest points. The values (Fig. 9) are 472 anyway much smaller than those found for sewer flow (Table 2 and Fig. 7). This apparent 473 contradiction is likely to be due to the fact that most of the rain water is properly handled by 474 sewers and overflows are limited for these events. It means that for these events disparities in 475 local amounts will not be visible on ground levels, whereas they are indeed in sewer flows 476 and water depths. Further investigations with heavier rainfall events should be carried out to 477 confirm or not this interpretation. The areas with the greatest uncertainty are found in gardens 478 for the weakest event (09-02-2009), and correspond to places with a very small maximum 479 depth (smaller that 1mm), meaning that the hydrological relevance is not very high.

480

481

482 5) Multifractal characterization of overland water depth

483 Multifractal analyses of overland water depth during rainfall event are presented in
484 this paper for the 14-07-2010 and 15-12-2011 events which are the two heaviest ones in terms
485 of maximum rainfall intensity over 5 min (see Table 1).

486 Figure 10.a displays the spectral analysis of the water depth for the 14-07-2011 event. 487 Maps of water depth for each time steps during the event are used to carry out 2D ensemble 488 analyses. The quality of the scaling is low, with a coefficient of determination for the linear 489 regression equal to 0.42. The fact that the spectral slope is close to zero (β is found roughly 490 equal to 0.2) indicates that the field is conservative, i.e. its mean is conserved across scales. It 491 is therefore possible to implement directly on the field a Trace Moment (TM) analysis, which 492 consists in assessing the validity of Eq. 4 by plotting it in log-log. Perfect UM fields would 493 lead to straight lines. Figure 10.b shows the TM ensemble analysis performed over all the 494 time steps of the same 14-07-2011 event. Two scaling regimes can be identified: a small

495 scales regime from 10 m to 80 m (right part of Fig. 10.b) and a large scales regime from 80 m to 1280 m (left part of Fig. 10.b). The coefficient of determination r^2 of the linear regression 496 497 for q=1.5 in Fig. 10.b is taken as an indication of the quality of the scaling. The scaling from 498 small scales (10 m - 80 m) is much more robust than for large scales (80 m to 1280 m), as illustrated by the r^2 equal to respectively 0.99 and 0.91. Given the low quality of the scaling 499 500 for large scales, UM parameter estimates will not be reported and discussed for this regime 501 because they are not reliable. Furthermore, small scales are crucial for surface runoff because 502 it is at these scales that it is generated into the drainage system. The location of this break at 503 approximately 80 m indicates a possible physical interpretation. Indeed, it is the same location 504 as the break in the fractal analysis of the sewer network and corresponds roughly to the inter-505 distance between roads. This would mean that this break is driven by the influence of the 506 collection of water by sewer network. The more robust scaling behaviour for surface flow is 507 found for the scales for which the sewer network does not behave yet as network but as 508 isolated linear pipes. Before going on, it should be mentioned that numerous pixels have very 509 small depth (see Fig. 8 for an illustration), for which the model uncertainties might be great. 510 These zeros values or spurious ones close to zero will affect the scaling analysis for small 511 moments (typically q < 0.5) through a multifractal phase transition (see Gires et al., 2012, for 512 a detailed analysis of this issue). Here the influence of this bias does not extend to moments 513 close to 1 around which the estimates of UM parameters are carried out, meaning that they are 514 not affected by this issue.

515

Although intrinsically less robust since scaling properties are statistical ones requiring numerous data to be properly observed, TM analyses were also carried out independently on each sampling time step of Multi-Hydro (3 min in this paper). The purpose is to see whether there is an impact of the current rainfall rate on it. Figure 11 displays for the 14-07-2010 event

the temporal evolution of both the rainfall rate and the r^2 for q=1.5 in the TM analysis for the 520 two regimes identified in the ensemble analysis, i.e. small (10 m - 80 m) and large scales (80 521 522 m - 1280 m). For this event, two rainfall peaks are observed, and they both result in a sudden loss of the scaling quality, more pronounced for large scales than small ones. For the first 523 peak (yellow bars on Fig. 11) the decrease of r^2 lasts approximately 20 min, while it lasts only 524 525 few minutes for the second peak (red bars on Fig 11). In both cases the quality of the scaling 526 behaviour improves again over few tens of minutes. The physical meaning of such loss is not 527 clear, but could be due to a bad representation of the surface flow process during intense 528 rainfall (it might take some time to retrieve a realistic surface flow simulation following a 529 sudden change in rainfall input), a bias in the geometrical repartition, or an intrinsic feature of 530 the process. For the latter, a possibility is that during intense rainfall period, the surface flow 531 exhibits more directly the rainfall features than its intrinsic ones which are retrieved once the 532 flow process has "adapted" to the new conditions. This would explain both the loss of scaling 533 quality and why scaling properties closer to rainfall ones are observed during these short 534 periods. Analysis with a higher resolution model would be needed to further investigate this 535 issue, which would also enable to have access to a wider range of small scales.

536 Similar features are retrieved for the other studied event (15-12-2011). Finally, it 537 should also be mentioned that similar results are also found when performing the analysis on 538 the North-South or West-East 1D-samples, which means that the preferential slope of the 539 catchment (North-South) does not seem to have an influence on the scaling features of the 540 simulated water depth. In terms of scaling quality, very similar results are also found with raw 541 radar data, or downscaled rainfall fields suggesting a limited impact of small scale rainfall 542 variability on these features. The same downscaling process as in section 2 is used.

543

544 UM parameters retrieved on the maximum water depth were computed for small 545 scales, and are displayed in Table 3 for the two events (14-07-2011 and 15-12-2012) and for 546 simulations with raw radar data and also a realisation of downscaled rainfall field with α =1.8 547 and *C*₁=0.1 (other realisations yield very similar results). The temporal evolutions of α and *C*₁ 548 for the 14-07-2011 event are shown in Figures 12.

It appears that the UM parameters are also affected by the "jumps" that were noticed 549 on r^2 in Fig. 11. Indeed after an intense period, sharp increase of α and decrease of C_1 are 550 551 noticed. These pronounced variations mean that the values obtained with ensemble analyses 552 should not be over-interpreted. Nevertheless few comments can be made. First the values of C_1 are much greater than the ones reported for rainfall (typically 0.1-0.3 at small scale) 553 554 meaning that significant levels of water depth are much more concentrated than the rainfall 555 field, which reflects the influence of the physical processes associated with surface flow on 556 the transferred field, notably the flow concentration. The most relevant one is the topography 557 that routes water through specific paths and tends to concentrate it. Second the values of UM 558 parameters are quite different between the two events. These differences are much greater 559 than the ones observed on the rainfall fields (see Ichiba, 2016, for a detailed analysis of these 560 storms) at small scales. This suggests that the large scales rainfall pattern has a strong 561 influence on the retrieved parameters. Indeed, the topography and small scale rainfall features 562 are the same between the two simulations; the only difference is the large scale rainfall 563 features. Thirdly the values of γ_s are rather similar for both events (the differences between α 564 and C_1 tend to compensate themselves).

565 The temporal evolutions of the UM parameters obtained by inputting raw and 566 downscaled rainfall data are very similar. The differences are slightly more pronounced on the 567 values computed on ensemble analysis but as previously said this should not be over-568 interpreted given the strong variations visible in the temporal analysis. This similarity

highlights the low influence of small scale rainfall variability on the retrieved parameters
which seems to be more dependent on features associated with surface flow process itself or
large scale rainfall.

572

In order to test the sensitivity of the results to small scales rainfall features, synthetic rainfall fields with various sets of known parameters are used as input to Multi-Hydro simulations. More precisely the pseudo-events tested last 30 min with an average intensity of 10 mm/h. Three pairs (α ; C₁) of parameters are tested: (1.8; 0.1), (1.8; 0.05), (1.4; 0.1). Figure 13 displays the temporal evolutions of the rain rates, r^2 , α and C₁ for water depth for the three synthetic rainfall events.

579 The temporal evolution shows the same general tendency as the one observed with the 580 real events. A loss of scaling quality is observed during the event itself, and it improves 581 afterwards. α and C_1 have a constant behaviour during the rainfall, while they decrease and 582 increase respectively after the rainfall has stopped. The comparison of the UM parameters for 583 the overland maximum water depth shows that they do not seem to depend on the small scale rainfall variability in this case. α is constant around 1.4 while C_1 is constant around 0.6 during 584 585 the rainfall. γ_s is again constant around 1.7 on average. The rainfall UM parameters do not 586 seem to modify the structure of the overland flow, and its geometrical distribution. Successive 587 simulations with the same parameters for synthetic rainfall yielded same results. A physical explanation of the C_1 parameter could be that during the rainfall, the surface flow is more 588 589 homogenous due to a ubiquitous input of water. UM parameters on water depth are thus 590 closer to the rainfall ones (small C_1). However after the rain has stopped, the disparities of 591 simulated water depth are increased due to predominant pathways (roads) or topographic 592 depressions where the water can accumulate. The greater C_1 after the event could reflect this

593 fact. The smaller values of α mean that the disparities among the areas where water remains 594 tend to decrease after the rainfall event.

This study seems to highlight the fact that UM parameters α and C_1 for water depth are rather relying on the large scale structure of the rainfall and on the catchment features, while the maximum observable singularity γ_s is conserved for all events. Further studies could infirm or confirm the fact that γ_s depends on the studied catchment. The temporal evolutions of the UM parameters also deeply rely on the rainfall rate. Synthetic events with block structures enabled to stand out rather simple general tendencies. They become more complex with real rainfall, when the intensity has a higher temporal variability.

The temporal evolutions of the UM parameters also enable to quantify a catchment response time. Due to the sampling time step of the simulations, the uncertainty associated with the response is of 3 min. Still, it can be noted that in urban catchments (or semi-urban here), the response time of water depth UM parameters to the beginning of a rainfall or to an important peak of intensity is almost non-existent. This is due to the presence of impervious area over which rainfall directly transfer into surface runoff.

608

609

610 6) Conclusions

611

The Multi-Hydro model was implemented on the Jouy-en-Josas catchment in the Paris area. This 3 km² semi-urbanised catchment exhibits sharp slopes, and a dense area along the Bièvre River bed. It has often been damaged by major pluvial and fluvial flooding, before the construction of storage basins along the river path. The model was validated on this new catchment on four rainfall events with the help of the data from a height gauge near the outlet. Rainfall radar data with a resolution of 1km x 1km x 5min was used.

618 Then ensembles of downscaled rainfall fields were used to quantify the sensitivity of 619 the model outputs to small scales unmeasured rainfall variability, i.e. occurring below the 620 resolution of the available raw radar data. It appears that it is rather significant on flow 621 simulated in conduits with pseudo coefficients of variations ranging from 90 % upstream to 10% downstream. This confirms previous results obtained on a 1.5 km² flat highly urbanised 622 623 catchment also in the Paris area. The methodology was extended here to simulated water 624 depth, and it was found that the sensitivity was much lower than for conduits' flow. This is 625 likely to be due to the fact that the sewer system is mainly able to cope with the storm water for these events limiting the amount of surface runoff. 626

627 After using them to downscale the radar data, Universal Multifractals are used in an 628 innovative way to characterize the surface flow process -through simulated water depth for 629 each 10 m x 10 m pixel over 3 min time steps- during rainfall events. UM parameters α and 630 C_1 , and the composite parameter γ_s are evaluated on the outputs of Multi-Hydro. Two scaling regimes are identified for this field and estimates are only reliable for small scales, i.e. 10m -631 632 80m, and related to the fractal feature of the sewer system which exhibits a scale break at the 633 same scale. There is a loss of the quality of the scaling during intense rainfall periods and UM 634 parameters get closer to rainfall ones. A possible interpretation is that during this short period, 635 a mixture of the scaling behaviour of both surface flow and rainfall is observed. After the 636 event scaling is improved and features more specific to surface flow processes are retrieved 637 with a field strongly concentrated and variability among the wet areas dampened (C_1 greater 638 than 1 and α smaller than 1). Small scale rainfall features do not seem to strongly influence 639 the results which depend more on large scales rainfall spatio-temporal patterns for these 640 events which do not trigger much sewer overflow.

641 The conclusions found with the help of this innovative methodology are not as642 straightforward as the authors would have hoped. Further investigations with other rainfall

643 events, other catchments, notably with denser monitoring network including in-sewer 644 measurements, should be carried out to strengthen the results. Higher resolution models 645 should also be tested to extend the range of available scales for the small scales regime to 646 obtain more reliable estimates of scaling features. Such new analysis would enable to 647 generalize the behaviour of the scaling and of the UM parameters which describes the surface 648 flows, and eventually to link them to other geometrical features of the catchment, such as the 649 fractal dimension of its impervious surface, of the roads (which are the preferential path for 650 surface flows) or of the sewer system. This paper should be seen as a promising first step that 651 hints at innovative techniques relying on scale invariance properties to analyse how the 652 rainfall extremes are either dampened or enhanced by hydrological models and also to 653 quantify the extremes at very high spatial resolution (typically 1 m) without having to run the 654 model at these resolutions which would require too much time especially for real time 655 applications. 656 657 658 Acknowledgments

Authors acknowledge partial financial support from the European Interreg IV RainGain
project (www.raingain.eu), the Chair "Hydrology for resilient cities" endowed by Veolia, and

the Ile-de-France regional R2DS RadX@IdF project. Authors would also like to thank Hervé

662	Cardinal	from	the S	SIAVB	for	providing	data	and	fruitful	discus	sions.
001	Caraman	110111	une s		101	provianne	anna	and	11 0111 01	anseas	010110.

663

- 664
- 665

666 6) References

- (EEA), E.E.A., 2014. <u>http://www.eea.europa.eu/articles/analysing-and-managing-urban-</u>
 growth (consulted on 20-10-2014).
- Bolle, A. et al., 2006. Hydraulic modelling of the two-directional interaction between sewer
 and river systems, Urban Drainage Modelling and Water Sensitive Urban Design,
 Merlbourne.
- 673 Carr, R.S. and Smith, G.P., 2006. Linking of 2D and Pipe hydraulic models at fine spatial
 674 scales, Urban Drainage Modelling and Water Sensitive Urban Design, Melbourne,
- 675 Australia.
- 676 Chen, A.S., Djordjević, S., Leandro, J. and Savić, D.A., 2007. The urban inundation model
- with bidirectional flow interaction between 2D overland surface and 1D sewernetworks, Proceedings of NOVATECH, Lyon, France.
- 679 Deltares, 2013. Sobek Suite V2.13, Deltares, Delft, NL.
- Despotovic, J., Plavsic, J., Stefanovic, N., Pavlovic D., 2005. Inefficiency of storm water
 inlets as a source of urban floods. Water Sci Technol, 15(2):139–145
- 682 Djordjevic, S., Prodanovic, D. and Maksimovic, C., 1999. An approach to simulation of dual
- drainage. Water Science and Technology, 39(9): 95-103.
- 684
- 685 Djordjević, S., Prodanović, D., Maksimović, Č., Ivetić, M., Savić D., 2005. SIPSON -
- 686 Simulation of Interaction between Pipe flow and Surface Overland flow in Networks.
 687 Water Science and Technology, 52 (5): 275-283.
- 688 Douglas, E.M. and Barros, A.P., 2003. Probable maximum precipitation estimation using
- multifractals: Application in the eastern United States. Journal of Hydrometeorology,
 4(6): 1012-1024.
- El Tabach, E., Tchiguirinskaia, I., Mahmood, O. and Schertzer, D., 2009. Multi-Hydro: a
 spatially distributed numerical model to assess and manage runoff processes in peri-

- 693 urban watersheds, Final conference of the COST Action C22 Urban Flood
- 694 Management, Paris 26/27.11.2009, France.
- Fletcher, T.D., Andrieu, H. and Hamel, P., 2013. Understanding, management and modelling
 of urban hydrology and its consequences for receiving waters: A state of the art.
 Advances in Water Resources, 51(0): 261-279.
- 698 Giangola-Murzyn, A. et al., 2014. Multi-Hydro : an open access coupling model for urban
 699 hydrology (submitted). Journal of Hydro-Informatics.
- 700 Gires, A., Schertzer, D., Tchiguirinskaia, I., Lovejoy, S., Maksimovic, C., Onof, C., Simoes,
- 701 N., 2011b. Impact of unmeasured rainfall variability on urban discharge: a case study
- in a multifractal framework. Houille Blanche Revue Internationale de l'Eau(4): 37-
- 703 42.
- Gires, A., Tchiguirinskaia, I., Schertzer, D. and Lovejoy, S., 2012. Influence of the zerorainfall on the assessment of the multifractal parameters. Advances in Water
 Resources, 45, 13-25.
- Gires, A., Tchiguirinskaia, I., Schertzer, D. and Lovejoy, S., 2013. Multifractal analysis of a
 semi-distributed urban hydrological model. Urban Water Journal, 10(3): 195-208.
- 709 Gires, A. et al., 2014a. Impacts of small scale rainfall variability in urban areas: a case study
- 710 with 1D and 1D/2D hydrological models in a multifractal framework. Urban Water
 711 Journal: 1-11.
- Gires, A. et al., 2014b. Influence of small scale rainfall variability on standard comparison
 tools between radar and rain gauge data. Atmospheric Research, 138(0): 125-138.
- 714 Gires, A., Tchiguirinskaia, I., Schertzer, D., Ochoa-Rodriguez, S., Willems, P., Ichiba, A.,
- 715 Wang, L.-P., Pina, R., Van Assel, J., Bruni, G., Murla Tuyls, D., and ten Veldhuis,
- 716 M.-C., 2017. Fractal analysis of urban catchments and their representation in semi-

- 717 distributed models: imperviousness and sewer system, Hydrol. Earth Syst. Sci., 21,
- 718 2361-2375, https://doi.org/10.5194/hess-21-2361-2017.
- Hsu, M.H., Chen, S.H. and Chang, T.J., 2000. Inundation simulation for urban drainage basin
 with storm sewer system. Journal of Hydrology, 234(1-2): 21-37.
- Hubert, P. et al., 1993. Multifractals and extreme rainfall events. Geophys. Res. Lett., 20:
 931-934.
- Ichiba, A. (2016). X-band radar data and predictive management in urban hydrology, Ph.D.
 thesis, Université Paris-Est.
- 725 Ichiba, A., Gires, A., Tchiguirinskaia, I., Schertzer, D., Bompard, P., and Ten Veldhuis, M.-
- C., 2017. Scale effect challenges in urban hydrology highlighted with a distributed
 hydrological model, Hydrol. Earth Syst. Sci., accepted.
- 728 Innovyze, 2012. InfoWorks CS v13.0.6.
- 729 Innovyze, 2013. Infoworks ICM v.3.5.
- 730 Institute, D.H., 2011. Mike Urban.
- 731 IPCC, 2013. Working Group 1 contribution to the IPCC fifth report climate change 2013: the

732 physical science basis, summary of policy makers. Technical report.

- 733 Jankowfsky, S., 2011. Understanding and modelling of hydrological processes in small peri-
- riban catchments using an object-oriented and modular distributed approach.
- 735 Application to the Chaudanne and Mercier sub-catchments (Yzeron catchment,
- 736 France). PhD Thesis., Lyon, France.
- 737 Parisi, G. and Frish, U., 1985. A multifractal model of intermittency. In: M. Ghill, R. Benzi
- and G. Parisi (Editors), Turbulence and predictability in geophysical fluid dynamics.
- 739 Elsevier North Holland, New-York, pp. 111-114.

- 740 Phillips, B., Yu, S., Thompson, G. and Silva, N., 2005. 1D and 2D Modelling of Urban
- 741 Drainage Systems using XP-SWMM and TUFLOW, 10th International Conference on
 742 Urban Drainage, Copenhagen, Denmark.
- 743 Pitt, M., 2008. The Pitt Review : Learning lessons from the 2007 floods,
- 744 http://webarchive.nationalarchives.gov.uk/20100807034701/http:/archive.cabinetoffic
- 745 <u>e.gov.uk/pittreview/thepittreview/final_report.html</u> (accessed 20-10-2014).
- 746 Richard, J., Giangola-Murzyn, A., Gires, A., Tchiguirinskaia, I. and Schertzer, D., 2014. Gis
- 747 data Assimilation interface for distributed hydrological models. Environmental
 748 Modelling and Software (submitted).
- 749 Rodriguez, F., Andrieu, H. and Morena, F., 2008. A distributed hydrological model for
- r50 urbanized areas model development and application to case studies. Journal of
 r51 Hydrology, 351: 268-287.
- Rossman, L.A., 2010. Storm Water Management Model, User's Manual. Version 5.0. U.S.
 Environmental Protection Agency, EPA/600/R-05/040.
- 754 Royer, J.-F., Biaou, A., Chauvin, F., Schertzer, D. and Lovejoy, S., 2008. Multifractal
- analysis of the evolution of simulated precipitation over France in a climate scenario.
 C.R Geoscience, 340: 431-440.
- Schertzer, D. and Lovejoy, S., 1987. Physical modelling and analysis of rain and clouds by
 anisotropic scaling and multiplicative processes. J. Geophys. Res., 92(D8): 96939714.
- 760 Schertzer, D. and Lovejoy, S., 2011. Multifractals, generalized scale invariance and
- 761 complexity in geophysics. International Journal of Bifurcation and Chaos, 21(12):
 762 3417-3456.

763	Shah, S.M.S., O'Connell, P.E. and Hosking, J.R.M., 1996. Modelling the effects of spatial
764	variability in rainfall on catchment response. 1. Formulation and calibration of a
765	stochastic rainfall field model. Journal of Hydrology, 175(1-4): 67-88.
766	Solution, X., 2012. XPSWMM V.12.
767	Tabary, P., 2007. The new French operational radar rainfall product. Part I: Methodology.
768	Weather and Forecasting, 22(3): 393-408.
769	Tabary, P. et al., 2007. The new French operational radar rainfall product. Part II: Validation.
770	Weather and Forecasting, 22(3): 409-427.
771	Velleux, M.L., England, J.F. and Julien, P.Y., 2011. TREX Watershed Modelling Framework
772	User's Manual: Model Theory and Description. Department of civil engineering, Colorado
773	State University, Fort Collins: 106p.
774	
775	

- 776 **Tables:**
- 777

	Radar rain depth (mm)	Rain gauge depth (mm)	Duration (min)	Peak intensity over 5 min (mm/h)
09-02-2009	9.4	Unavailable	725	5.12
14-07-2010	43.2	35.2	1020	52.06
15-08-2010	27.8	20.8	1745	7.56
15-12-2011	26.2	29.6	785	24.26

Table 1: Main features for the four studied rainfall events. Cumulative depth are computed

over the whole event. For the radar data averages over the catchment are displayed.

Event / Link	#1	#2	#3	#4	#5
09-02-2009	63 / 16	35 / 15	10 / 7.2	4.0 / 1.7	4.8 / 2.1
14-07-2010	76 / 22	27 / 13	7.1 / 3.6	7.5 / 3.2	7/3.1
15-08-2010	70 / 20	38 / 16	26 / 12	9.3 / 3.9	8.5 / 3.8
15-12-2011	60 / 23	50 / 22	28 / 12	11 / 4.1	8.7 / 3.9

Table 2: CV'_{95} and CV'_{75} in % (first and second figure respectively) for the five selected

conduits and four rainfall events.

Event	Rainfall input	α	C_1	γs
14-07-2010	Raw radar data	1.55	0.62	1.52
	Downscaled rainfall	1.25	0.90	1.68
15-12-2011	Raw radar data	0.95	1.42	1.74
	Downscaled rainfall	0.99	1.22	1.65

 Table 3: UM parameters for small scales (10 m - 80 m) computed with the help of a 2D

analysis with either raw radar data or a realisation of downscaled rainfall field (with α =1.8

and $C_1=0.1$) as rainfall input for the 14-07-2010 and 15-12-2011 events.

- 795 Figure captions:
- 796
- 797



- Figure 1: Maps of the Jouy-en-Josas catchment: (left) aerial photography and sewer system
- 800 (The green portion of the sewer network corresponds to the portion over which validation is
- 801 possible), (right) elevation in m.



- 803 Figure 2: Map of the land use obtained with the help of MH-AssimTool over the Jouy-en-
- 804 Josas catchment for two different resolutions.



Figure 3: (a) Evaluation of the fractal dimension of the impervious area for the studied
catchment (Eq. 1 in log-log plot). The circle points correspond to the figures obtained from
the map generated with the help of MH-AssimTool at various resolutions. (b) Evaluation of
the fractal dimension of the sewer system.



Figure 4: Average over the catchment of the rainfall radar intensity in mm/h over 5 min time
steps for the four events: (a) 09-02-2009, (b) 14-07-2010, (c) 15-08-2010, (d) 15-12-2011



815 Figure 5: Illustration of the samples studied in the multifractal analysis of overland water

816 depth at the end of each 3-min Multi-Hydro loop: (a) 2D maps, (b) 1D vertical columns (N-S

817 direction), (c) 1D horizontal rows (W-E direction).



818

819 Figure 6: Water height simulated with the help of Multi-Hydro using raw radar data as rainfall

820 input, and measurements at the Pont-de-Pierre for the four events: (a) 09-02-2009, (b) 14-07-

^{821 2010, (}c) 15-08-2010, (d)15-12-2011



822

Figure 7: Simulated flow with the raw radar data (black), $Q_{0.25}$ and $Q_{0.75}$ (dark pink colour), $Q_{0.05}$ and $Q_{0.95}$ (light pink colour) for 5 conduits of the studied catchment for the 09-02-2009 event.



Figure 8: For the 15-12-2011 event. (a) Map of the computed maximum water depth for a
realisation of the downscaled rainfall field. (b) 5% quantile map of the maximum water depth
over 100 realisations. (b) 95% quantile map of the maximum water depth over 100
realisations. Unit is m.



Figure 9: Map of CV'_{95} (in %) for the maximum water depth for the 09-02-2009 (a), 15-08-

- 833 2010 (b) and 15-12-2011 (c) events.
- 834



836 Figure 10: For the 14-07-2010 event and 2D ensemble analysis over all the time steps: (a)





Figure 11: For the 14-07-2010 event: (a) Temporal evolution of the rain rate; (b) Temporal evolution of the r^2 for q=1.5 in the TM analysis for the two regimes identified in Fig. 10.



Figure 12: Temporal evolution of the UM parameters α and C_1 of the maximum water depth

843 field over 3 min for small scales (10 - 80 m) for the 14-07-2010 rainfall event.



845

Figure 13: For three synthetic rainfall events with different sets of UM parameters; temporal evolution of the average rain rate over the catchment (a), and for the simulated overland maximum water depth, r^2 (b), α (c) and C_1 (d) for small scales (10 m-80 m).