Semantizing Complex 3D Scenes using Constrained Attribute Grammars



A. Boulch, S. Houllier, R. Marlet and O. Tournaire

slight variant of the material presented at SGP 2013

Semantizing complex objects in 3D scenes



Bare geometry

Semantized geometry

Semantizing complex objects in 3D scenes



Bare geometry

Semantized geometry (rendered)

Semantizing complex objects in 3D scenes

- Building industry
 - $\hfill\square$ for the renovation market
 - $\blacksquare \text{ point cloud} \rightarrow \text{building model}$



Semantized geometry

Semantizing complex objects in 3D scenes

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 - $\hfill\square$ for the renovation market
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 - \Box for architects
 - building sketch \rightarrow rendering



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 - point cloud → building model
 - \Box for architects
 - building sketch \rightarrow rendering
- Game industry
 - □ for graphic designers
 - basic level design → rendering



Semantized geometry (rendered)

Semantizing complex objects in 3D scenes

- Building industry
 - for the renovation market
 - point cloud → building model
 - □ for architects
 - building sketch \rightarrow rendering
- Game industry
 - □ for graphic designers
 - basic level design \rightarrow rendering
- Object mining in shape databases
 - □ for semantic queries
 - 3D object \rightarrow semantic labeling



Semantized geometry

Constrained attribute grammars

Scene interpretation

Bottom-up parsing

Experiments



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Grammars to express hierarchical decomposition



Complex, non-hierarchic relations between components



Constrained attribute grammars

- G = (N, T, P, S)
- N: nonterminals (\leftrightarrow complex forms) e.g., window, wall
- T: terminals (\leftrightarrow geometric primitives) e.g., polygon, cylinder
- P: production rules (\leftrightarrow hierarchical decomposition and constraints)
- S: start symbols (\leftrightarrow root shapes)

e.g., building

Basic rules

Decomposition of a complex object y of type Y into its constituents x_i of type X_i :

$$Y y \longrightarrow X_1 x_1, \ldots, X_n x_n$$

Example:

step
$$s \longrightarrow riser r$$
, tread t

Rule application:

top-down view:

y decomposes into x_1, \ldots, x_n

bottom-up view:

given some x_1, \ldots, x_n , create a new object y



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Conditional rule application (conjonction of predicates):

$$Y y \longrightarrow X_1 x_1, X_2 x_2, \dots \langle cstr_1(x_1), cstr_2(x_1, x_2), \dots \rangle$$



Attributes

Features attached to each grammar element:

- at creation time (primitives)
- at rule application (synthetized attributes)

Examples:

- length, width
- bounding box



. . .

Predicates

Predicates on grammar elements:

- adj, edgeAdj
- orthogonal, parallel
- vertical, horizontal
- · · · ·

Predicates on attributes:

$$\geq , >, \leq , \dots$$
$$= , \neq$$



Example: *r*.*length* == *t*.*length*

Collections of similar elements

Grouping elements via recursion (Y as set of Xs):

Grouping elements via specific collection operators: $Y \ y \longrightarrow coll(X) \ xs$

Useful operators: maximal collections

- maxconn: maximal set of connected components
- maxseq: maximal sequence

· · · ·

Example:

stairway sw → maxseq(step, adjEdge) ss

Collections of similar elements

Grouping elements via recursion (Y as set of Xs):

$$\begin{array}{ccccccc} Y & y & \longrightarrow & X & x \\ Y & y & \longrightarrow & X & x, Y & y_2 \end{array}$$

Grouping elements via specific collection operators:

 $Y y \longrightarrow coll(X) xs$

Useful operators: maximal collections

- maxconn: maximal set of connected components
- maxseq: maximal sequence

[see complete stairway grammar]

Example:

. . .

stairway sw → maxseq(*step*, *adjEdge*) *ss*

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Scene interpretation: parse tree

Tree representation of a grammatical analysis of the scene:

- leaves: terminals representing primitives
- non-leaf nodes: instanciations of grammar rules



Scene interpretations: parse forest

Set of parse trees with systematic sharing (DAG)

Compact representation of all possible interpretations



Ambiguity and the exclusivity constraint

Example (assuming no height ordering constraint):

step s \longrightarrow riser r, tread t $\langle edgeAdj(r, t) \rangle$



Exclusivity constraint: at most 1 occurrence of a grammar element per interpretation



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Parse forest computation

Bottom-up parsing:

construction of the parse forest

from leaves (terminals) to roots (start symbols)

create one terminal for each primitives

iteratively create new grammar elements from existing ones

□ e.g., given grammar rule step $s \longrightarrow riser r$, tread t given existing instances riser r_{23} , tread t_{18} create new instance step s_5

merge identical trees on the fly

stop iterating when no rule applies

Rule application order

- Simple rules: use any order
- Maximal operators: wait for all subelements to ensure maximality



Rule application order

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Rule application order

- Simple rules: use any order
- Maximal operators: wait for all subelements to ensure maximality
 reverse topological sort of nonterminal dependency graph



Mastering the combinatorial explosion

Usual drawback of bottom-up analysis: combinatorial explosion

- all trees
- all sets, all sequences, ...
- all combinations

Our solution:

- tree sharing: construction of a parse forest $(exp. \rightarrow lin.)$
- maximal operators, with efficient implementation (> exp. \rightarrow polyn.)
- constraint propagation: predicate ordering ⇒ early pruning

Maximal operators



Maximal operators



Constraint propagation as predicate ordering A simple 2D example

pair $p \longrightarrow seg s_1, seg s_2, \ \langle orthogonal(s_1, s_2), adj(s_1, s_2), vertical(s_1) \rangle$



pair $p \longrightarrow seg s_1, seg s_2, \ \langle orthogonal(s_1, s_2), adj(s_1, s_2), vertical(s_1) \rangle$

1. orthogonality

Complexity: $O(\# seg^2)$



constraints to test

pair $p \longrightarrow seg s_1, seg s_2, \ \langle orthogonal(s_1, s_2), adj(s_1, s_2), vertical(s_1) \rangle$

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satisfied constraints

pair $p \longrightarrow seg s_1, seg s_2, \ \langle orthogonal(s_1, s_2), adj(s_1, s_2), vertical(s_1) \rangle$

- 1. orthogonality
- 2. adjacency

Complexity: $O(\#seg^2 + \#seg \times maxDeg)$ $= O(\#seg^2)$



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satisfied constraints

pair $p \longrightarrow seg s_1, seg s_2, \langle orthogonal(s_1, s_2), adj(s_1, s_2), vertical(s_1) \rangle$

- 1. orthogonality
- 2. adjacency
- 3. verticality

Complexity: $O(\#seg^2 + \#seg \times maxDeg + \#seg)$ $= O(\#seg^2)$



constraints to test

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constraints to test

pair $p \longrightarrow seg s_1, seg s_2, \langle orthogonal(s_1, s_2), adj(s_1, s_2), vertical(s_1) \rangle$

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satisfied constraints

pair $p \longrightarrow seg s_1, seg s_2, \ \langle orthogonal(s_1, s_2), adj(s_1, s_2), vertical(s_1) \rangle$

- 1. verticality
- 2. adjacency

Complexity : $O(\#seg + \#seg \times maxDeg)$ $= O(\#seg \times maxDeg)$



constraints to test

pair $p \longrightarrow seg s_1, seg s_2, \langle orthogonal(s_1, s_2), adj(s_1, s_2), vertical(s_1) \rangle$

- 1. verticality
- 2. adjacency
- 3. orthogonality

Complexity : $O(\#seg + \#seg \times maxDeg + \#seg \times maxDeg + \#seg \times maxDeg)$ $= O(\#seg \times maxDeg) \ll O(\#seg^2)$



Constraint propagation as predicate ordering

1. Unary predicates

= constraints implying only 1 element: complexity O(# element)Example:

riser $r \longrightarrow polygon p \langle vertical(p) \rangle$

Constraint propagation as predicate ordering

- 1. Unary predicates
- 2. Invertible predicates that are partially instantiated

= constraints with small cardinality when some arguments are fixed Example:

step s
$$\longrightarrow$$
 riser r, tread t $\langle edgeAdj(r,t) \rangle$

Constraint propagation as predicate ordering

- 1. Unary predicates
- 2. Invertible predicates that are partially instantiated
- 3. General predicates
- = remaining relations

Example:

step s \longrightarrow riser r, tread t $\langle orthogonal(r, t) \rangle$

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Semantization pipeline



CAD models

Preprocessing

- Region growing over triangles for polygon creation
- Computation of exact and approximate adjacency graphs



CAD models

Detection of stairs

(more examples in supplem. material)



CAD models

Detection of walls, roofs and openings

(more examples in supplem. material)





Real data: photogrammetry

- Preprocessing (point cloud)
 - clustering using RANSAC (or region growing)
 - polygons bounded
 by alpha shapes
- Problems:
 - missing primitives
 - □ false primitives
 - wrong adjacencies
- Solution:
 - $\hfill\square$ use of a relaxed grammar
 - looser bounds
 - 1-2 missing items OK
 - □ 22 openings out of 31



Quasi-real data: simulated LIDAR



- Planes by region growing in depth image
- Polygons as oriented bounding rectangles
- Adjacency based on pixels in depth image

Size and parsing time (CAD models)

	# of	# of	Parsing time (s)		
Name	triangles	polygons	stairs	openings	
LcG	48332	9705	5	15	
LcA	111979	26585	14	42	
LcC	385541	111732	33	306	
LcD	313012	75257	25	111	
LcF	286996	84347	39	322	

Precision and recall (%, CAD models)

	# of	# of	Stairs		Openings		
Name	stairs	steps	Prec.	Rec.	#	Prec.	Rec.
LcG	3	45	100	93	83	100	90
LcA	6	84	100	100	62	98	83
LcC	30	210	100	100	196	100	98
LcD	5	61	93	100	74	100	93
LcF	7	98	100	50	99	100	96

- Principled way to deal with partial or missing primitives
- Exploitation of occlusion/visibility information
- Scoring of interpretations: pick best tree(s)

Conclusion

Constrained attribute grammars:

- appropriate to semantize complex objects
- high-level specification language
 - being expert is enough, computer scientist not required
- efficient even on large models

This work:

- well-delimited first step: perfect data
- extensions required for incomplete/noisy data

On the web

http://imagine.enpc.fr/

sites.google.com/site/boulchalexandre/